# GMM estimation of a spatial autoregressive model with autoregressive disturbances and endogenous regressors 

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#### Abstract

This paper considers the generalized method of moments (GMM) estimation of a spatial autoregressive (SAR) model with SAR disturbances, where we allow for endogenous regressors in addition to a spatial lag of the dependent variable. We do not assume any reduced form of the endogenous regressors, thus we allow for spatial dependence and heterogeneity in endogenous regressors, and allow for nonlinear relations between endogenous regressors and their instruments. Innovations in the model can be homoskedastic or heteroskedastic with unknown forms. We prove that GMM estimators with linear and quadratic moments are consistent and asymptotically normal. In the homoskedastic case, we derive the best linear and quadratic moments that can generate an optimal GMM estimator with the minimum asymptotic variance.


Keywords: Spatial autoregression, endogeneity, GMM, heteroskedasticity, efficiency
JEL classification: C13, C21, C31, C36, R15

## 1 Introduction

Spatial autoregressive (SAR) models are popular spatial econometric models in empirical research. Various estimation methods for SAR models have been considered, including, among others, the

[^0]two stage least squares (2SLS) (Lee, 2003), the quasi maximum likelihood (QML) (Ord, 1975; Lee, 2004), and the generalized method of moments (GMM) (Lee, 2007). QML is relatively computationally intensive, since it involves the computation of the determinants of square matrices with their dimensions equal to the sample size. GMM can employ both linear moments characterizing instrumental variables (IV) and quadratic moments capturing spatial dependence, which are motivated from the QML estimation. Thus, GMM estimators are generally more efficient than 2SLS estimators. They are also computationally simpler than QML estimators, because they avoid the computation of determinants. The generalized spatial two stage least squares (GS2SLS) in Kelejian and Prucha (1998) is a multiple-step method specially designed for SAR models with SAR disturbances (SARAR models). It is computationally simple, but parameters in the equation for the dependent variable are estimated using only linear moments. When innovations in SAR models are heteroskedastic with unknown forms, the GMM and GS2SLS estimators are studied in, respectively, Lin and Lee (2010) and Kelejian and Prucha (2010). Liu and Yang (2015) propose a modified QML method, where QML first order conditions are modified to be valid under unknown heteroskedasticity and consistent estimators are derived by solving the modified first order conditions.

SAR models that allow for endogenous regressors in addition to spatial lags of the dependent variable have also been studied in the literature. Fingleton and Le Gallo (2008) and Drukker et al. (2013) investigate the GS2SLS estimation, Liu (2012) considers the limited information maximum likelihood (LIML) estimation, Liu and Lee (2013) study the 2SLS estimation, and Liu and Saraiva (2015) propose the GMM estimation. As for SAR models without endogenous regressors, likelihood based methods are relatively intensive in computation, and GMM can be computationally simple and relatively efficient asymptotically. Gupta and Robinson (2015) and Gupta (2019) have also considered the 2SLS estimation of SAR models with endogenous regressors, in the context of increasingly many parameters or stochastic spatial weights matrices.

We note that Liu and Saraiva (2015) assume a linear reduced form for endogenous regressors when considering GMM estimators. ${ }^{1}$ The reduced form excludes any spatial dependence and heterogeneity in the endogenous regressors, which might arise for spatial variables. It also excludes any nonlinear relation between the endogenous regressors and their IVs. As the reduced form is used to form moment conditions, if it is misspecified, then the GMM estimators will no longer be consistent in general. Fingleton and Le Gallo (2008) and Drukker et al. (2013) have not assumed reduced forms for endogenous regressors when they consider the GS2SLS estimation, but the GS2SLS estimator is asymptotically less efficient than the GMM estimator that employs both linear and quadratic moments, as mentioned above.

[^1]In this paper, we consider the GMM estimation of an SARAR model with endogenous regressors, by employing both linear and quadratic moments. Firstly, we do not impose any reduced form of endogenous regressors. Secondly, we study both the cases with homoskedastic and heteroskedastic model innovations. Thus, our paper extends the study on SAR models with unknown heteroskedasticity to the case with both unknown heteroskedasticity and endogenous regressors. We prove that GMM estimators are consistent and asymptotically normal under regularity conditions. Lastly, in the homoskedastic case, among a class of GMM estimators with linear and quadratic moments, we derive the best one with a minimum asymptotic variance. The best GMM estimator can guide our selection of linear and quadratic moments.

This paper is organized as follows. Section 2 studies large sample properties of our proposed GMM estimators, Section 3 reports some Monte Carlo results on the finite sample performance of our GMM estimators, and Section 4 concludes. Proofs are collected in an Appendix.

## 2 GMM estimation

We consider the following SAR model with SAR disturbances and endogenous regressors:

$$
\begin{equation*}
Y_{n}=\lambda W_{n} Y_{n}+Z_{n} \gamma+X_{n} \beta+u_{n}, u_{n}=\rho M_{n} u_{n}+\epsilon_{n}, \tag{1}
\end{equation*}
$$

where $n$ is the sample size, $Y_{n}$ is an $n \times 1$ vector of observations on the dependent variable, $W_{n}$ and $M_{n}$ are $n \times n$ spatial weights matrices with zero diagonals, $Z_{n}$ is an $n \times k_{z}$ matrix of observations on endogenous regressors, $X_{n}$ is an $n \times k_{x}$ matrix of observations on exogenous regressors, $\epsilon_{n}=\left[\epsilon_{n 1}, \cdots, \epsilon_{n n}\right]^{\prime}$ is an $n \times 1$ vector of independent disturbances with zero means, $\lambda$ and $\rho$ are scalar spatial dependence parameters, $\gamma$ is a $k_{z} \times 1$ parameter vector, and $\beta$ is a $k_{x} \times 1$ parameter vector. The exogenous variable matrix is assumed to be nonrandom for simplicity, and $Z_{n}$ is stochastic. The spatial weights matrices $W_{n}$ and $M_{n}$ may or may not be the same in practice. We shall consider both the case where $\epsilon_{n i}$ 's are i.i.d. with mean zero and variance $\sigma_{0}^{2}$, and the case where $\epsilon_{n i}$ 's are independent with mean zero but they may have different variances $\sigma_{n i}^{2}$ 's. Let $\theta=\left[\lambda, \rho, \gamma^{\prime}, \beta^{\prime}\right]^{\prime}$ and $\theta_{0}=\left[\lambda_{0}, \rho_{0}, \gamma_{0}^{\prime}, \beta_{0}^{\prime}\right]^{\prime}$ be the true value of $\theta$. Denote $S_{n}(\lambda)=I_{n}-\lambda W_{n}$, $R_{n}(\rho)=I_{n}-\rho M_{n}, S_{n}=S_{n}\left(\lambda_{0}\right)$ and $R_{n}=R_{n}\left(\rho_{0}\right)$, where $I_{n}$ is the $n \times n$ identity matrix. ${ }^{2}$ Provided that $S_{n}$ and $R_{n}$ are invertible, $Y_{n}=S_{n}^{-1}\left(Z_{n} \gamma_{0}+X_{n} \beta_{0}+R_{n}^{-1} \epsilon_{n}\right)$.

Fingleton and Le Gallo (2008) and Drukker et al. (2013) have considered the GS2SLS estimation of model (1) with homoskedastic $\epsilon_{n i}$ 's. The GS2SLS estimation has several steps, which makes the computation easy, but the derivation of the joint asymptotic distribution of final estimators is relatively complicated. For the estimation of the parameters $\lambda, \gamma$ and $\beta$ in the equation for $Y_{n}$, only linear moments are used, but quadratic moments are not.

[^2]Liu (2012) and Liu and Saraiva (2015) consider the estimation of model (1) with no SAR process on $u_{n}$, where $u_{n}=\epsilon_{n}$ and $Z_{n}$ contains a single endogenous regressor. They assume that $Z_{n}$ has a reduced form

$$
\begin{equation*}
Z_{n}=F_{n} \delta+v_{n}, \tag{2}
\end{equation*}
$$

where $F_{n}$ is an $n \times k_{f}$ matrix of exogenous variables, $\delta$ is a $k_{f} \times 1$ vector of coefficients, and $v_{n}$ is a vector of i.i.d. disturbances which may correlate with $\epsilon_{n}$ in (1). The reduced form (2) specifies a fixed and restrictive linear relation between $Z_{n}$ and $F_{n}$. It does not allow for spatial dependence in $Z_{n}$, unless variables in $F_{n}$ show spatial dependence. The i.i.d. disturbances also exclude heterogeneity in $Z_{n}$. With (2) imposed, Liu (2012) considers the LIML estimation, and Liu and Saraiva (2015) consider the GMM estimation with moment conditions that are linear and quadratic forms of $\left[\epsilon_{n}^{\prime}, v_{n}^{\prime}\right]^{\prime}$ at the true parameter values. Thus, if (2) is misspecified, then their estimators will be inconsistent in general.

We consider the estimation of model (1) without imposing a reduced form of $Z_{n}$. As no reduced form is imposed, a likelihood or quasi likelihood function might not be formulated. We investigate a GMM estimator with the following moment vector:

$$
\begin{equation*}
g_{n}(\theta)=\frac{1}{n}\left[\epsilon_{n}^{\prime}(\theta) P_{1 n} \epsilon_{n}(\theta), \cdots, \epsilon_{n}^{\prime}(\theta) P_{k_{p} n} \epsilon_{n}(\theta), \epsilon_{n}^{\prime}(\theta) Q_{n}\right]^{\prime} \tag{3}
\end{equation*}
$$

where $\epsilon_{n}(\theta)=R_{n}(\rho)\left[S_{n}(\lambda) Y_{n}-Z_{n} \gamma-X_{n} \beta\right], P_{j n}$ 's are $n \times n$ matrices, and $Q_{n}$ is an $n \times k_{q}$ IV matrix. The total number of moments $k_{g}=k_{p}+k_{q}$ is non-smaller than the total number of parameters $k_{\theta}=2+k_{z}+k_{x}$. In the homoskedastic case, $P_{j n}$ 's are required to have zero traces, as $\mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n} \epsilon_{n}\right)=\sigma_{0}^{2} \operatorname{tr}\left(P_{j n}\right)$; in the heteroskedastic case, $P_{j n}$ 's are required to have zero diagonals, as $\mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n} \epsilon_{n}\right)=\operatorname{tr}\left(P_{j n} \Sigma_{n}\right)$ is a weighted sum of the diagonal elements of $P_{j n}$, where $\Sigma_{n}=$ $\operatorname{diag}\left(\sigma_{n 1}^{2}, \ldots, \sigma_{n n}^{2}\right)$ is a diagonal matrix of $\sigma_{n i}^{2}$ 's. The $P_{j n}$ 's can be, e.g., $W_{n}, M_{n}, W_{n}^{2}-I_{n} \operatorname{tr}\left(W_{n}^{2}\right) / n$ and $M_{n}^{2}-I_{n} \operatorname{tr}\left(M_{n}^{2}\right) / n$ in the homoskedastic case, and they can be $W_{n}, M_{n}, W_{n}^{2}-\operatorname{diag}\left(W_{n}^{2}\right)$ and $M_{n}^{2}-\operatorname{diag}\left(M_{n}^{2}\right)$ in the heteroskedastic case, where $\operatorname{diag}(A)$ for a square matrix $A$ denotes a diagonal matrix formed by the diagonal elements of $A$. The quadratic moments for SAR models are motivated from the QML estimation, which may significantly improve the estimation efficiency for SAR models (Lee, 2007; Lin and Lee, 2010). If $Z_{n}$ has an IV $F_{n}$, then the IV matrix $Q_{n}$ can be the matrix formed by the independent columns of $\left[X_{n}, F_{n}, W_{n} X_{n}, W_{n} F_{n}, W_{n}^{2} X_{n}, W_{n}^{2} F_{n}\right]$. The GMM estimator $\hat{\theta}_{\text {GMM }}$ with the moment vector $g_{n}(\theta)$ and a weighting matrix $a_{n}^{\prime} a_{n}$ has the objective function

$$
\begin{equation*}
\min _{\theta \in \Theta} g_{n}^{\prime}(\theta) a_{n}^{\prime} a_{n} g_{n}(\theta) \tag{4}
\end{equation*}
$$

where $\Theta$ is the parameter space of $\theta$, and $a_{n}$ is a $k_{a} \times k_{g}$ matrix with a limit $a_{0}$ by design. Here the row dimension $k_{a}$ can be greater or non-greater than $k_{g}$ for generality.

Some basic regularity conditions are summarized in the following assumptions.

Assumption 1. Either (a) $\epsilon_{n i}$ 's in $\epsilon_{n}=\left[\epsilon_{n 1}, \ldots, \epsilon_{n n}\right]^{\prime}$ are i.i.d. $\left(0, \sigma_{0}^{2}\right)$ and the moment $\mathrm{E}\left(\left|\epsilon_{n i}\right|^{4+\iota}\right)$ exists for some $\iota>0$, or (b) $\epsilon_{n i}$ 's are independent with mean zero and variances $\sigma_{n i}^{2}$ 's, and $\sup _{n} \sup _{1 \leq i \leq n} \mathrm{E}\left(\left|\epsilon_{n i}\right|^{4+\iota}\right)<\infty$ for some $\iota>0 .^{3}$

Assumption 2. The $W_{n}$ and $M_{n}$ have zero diagonals, and $\left\{W_{n}\right\},\left\{M_{n}\right\},\left\{S_{n}^{-1}\right\}$ and $\left\{R_{n}^{-1}\right\}$ are bounded in both row and column sum matrix norms.

Assumption 3. Elements of $X_{n}$ and $\mathrm{E}\left(Z_{n}\right)$ are uniformly bounded constants, and $\lim _{n \rightarrow \infty} \frac{1}{n} X_{n}^{\prime} X_{n}$ exists and is positive definite.

Assumption 4. Elements of $Q_{n}$ are uniformly bounded constants, and $\left\{P_{j n}\right\}$ for $j=1, \ldots, k_{p}$ are bounded in both row and column sum matrix norms.

Assumption 5. The parameter space $\Theta$ of $\theta$ is a compact subset of $\mathbb{R}^{k_{\theta}}$.
In Assumption 1, the existence of moments of disturbances with an order higher than four is for the applicability of a central limit theorem for linear and quadratic forms in Kelejian and Prucha (2001). In Assumption 2, the diagonal elements of $W_{n}$ and $M_{n}$ are required to be zero to exclude self-influence. The boundedness condition on spatial weights matrices, originated in Kelejian and Prucha (1998, 1999), is a standard condition in the spatial econometric literature that limits the degree of spatial dependence to be manageable. Since the analysis involves the matrix inverses $S_{n}^{-1}$ and $R_{n}^{-1}$, they are also assumed to be bounded in both row and column sum matrix norms. In Delgado and Robinson (2015) and Gupta and Robinson (2018), the consistency of relevant estimators is proved under the assumption of boundedness in the spectral norm of related matrices, although asymptotic distributions are still proved under the assumption of boundedness in the row and column sum norms. Since the spectral norm is non-greater than the row and column sum norms, their assumption is weaker. We also provide in Appendix D a proof of the consistency of our GMM estimator under the weaker assumption. As in Lee (2004), elements of $X_{n}$ are assumed to be nonstochastic for simplicity in Assumption 3. In Assumption 4, elements of $Q_{n}$ are also assumed to be constants, as $Q_{n}$ can be functions of $X_{n}, W_{n}, M_{n}$ and other IVs; and the boundedness condition on $P_{j n}$ 's is similar to that on $W_{n}$ and $M_{n}$, as $P_{j n}$ 's relate to $W_{n}$ and $M_{n}$. The compactness of the parameter space in Assumption 5 is standard for an extremum estimator.

We now discuss the identification condition for $\lim _{n \rightarrow \infty} \mathrm{E}\left[g_{n}(\theta)\right]$ to be uniquely zero at $\theta=\theta_{0}$. Denote $\bar{Z}_{n}=\mathrm{E}\left(Z_{n}\right)$ and $\check{Z}_{n}=Z_{n}-\bar{Z}_{n}$. Due to the endogeneity of $Z_{n}, \operatorname{cov}\left(\check{Z}_{n}, \epsilon_{n}\right) \neq 0$. Using $Y_{n}=S_{n}^{-1}\left(Z_{n} \gamma_{0}+X_{n} \beta_{0}+R_{n}^{-1} \epsilon_{n}\right)$, we have

$$
\begin{equation*}
\mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=Q_{n}^{\prime} \bar{\epsilon}_{n}(\theta) \tag{5}
\end{equation*}
$$

[^3]\[

$$
\begin{equation*}
\mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]=\bar{\epsilon}_{n}^{\prime}(\theta) P_{j n} \bar{\epsilon}_{n}(\theta)+\mathrm{E}\left[\check{\epsilon}_{n}^{\prime}(\theta) P_{j n} \check{\epsilon}_{n}(\theta)\right] \tag{6}
\end{equation*}
$$

\]

where

$$
\begin{align*}
& \bar{\epsilon}_{n}(\theta)=R_{n}(\rho)\left[\left(\lambda_{0}-\lambda\right) T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right)+\bar{Z}_{n}\left(\gamma_{0}-\gamma\right)+X_{n}\left(\beta_{0}-\beta\right)\right],  \tag{7}\\
& \check{\epsilon}_{n}(\theta)=R_{n}(\rho)\left[R_{n}^{-1} \epsilon_{n}+\left(\lambda_{0}-\lambda\right) T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right)+\check{Z}_{n}\left(\gamma_{0}-\gamma\right)\right] \tag{8}
\end{align*}
$$

with $T_{n}=W_{n} S_{n}^{-1}$. When $(\lambda, \gamma, \beta)=\left(\lambda_{0}, \gamma_{0}, \beta_{0}\right)$, as $\bar{\epsilon}_{n}(\theta)=0, \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=0$ for any $\rho$, so the linear moments alone are not enough to identify the parameter $\rho_{0}$ in the disturbance process. But it is possible to identify other parameters from the linear moments. If $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+\right.\right.$ $\left.\left.X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has full column rank for any $\rho$ in its parameter space $\boldsymbol{\rho}$, then the linear moment part of $\lim _{n \rightarrow \infty} \mathrm{E}\left[g_{n}(\theta)\right]=0$, i.e. $\lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=0$, implies that $(\lambda, \gamma, \beta)=\left(\lambda_{0}, \gamma_{0}, \beta_{0}\right)$. It is possible that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has reduced column rank for some $\rho \in \boldsymbol{\rho}$, then the identification of some parameters in $(\lambda, \gamma, \beta)$ would reply on the quadratic moments. Sufficient conditions for $\lim _{n \rightarrow \infty} \mathrm{E}\left[g_{n}(\theta)\right]$ to be uniquely zero at $\theta=\theta_{0}$ is presented in the following assumption.

Assumption 6. Either (i) $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has full column rank for any $\rho \in \rho$, and (C.2) or (C.3) holds; or (ii) $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho) X_{n}$ has full column rank for any $\rho \in \boldsymbol{\rho}$, and (C.4) holds.

Lemma 1. Under Assumption 6, for $\theta \in \Theta, \lim _{n \rightarrow \infty} \mathrm{E}\left[g_{n}(\theta)\right]$ is uniquely zero at $\theta=\theta_{0}$.
The identification conditions in Assumption 6 can be compared with the corresponding Assumptions 7-8 in Drukker et al. (2013). The estimation in Drukker et al. (2013) is carried out in several steps, where the parameters $(\lambda, \gamma, \beta)$ are estimated by 2SLS and the parameter $\rho$ is estimated with moments quadratic in residuals computed using the first step estimate, thus their identification conditions are more similar to the conditions in Assumption 6(i), where $(\lambda, \gamma, \beta)$ is identified from the linear moments and $\rho$ is identified from the quadratic moments. Since our GMM approach estimates $\rho$ jointly with $(\lambda, \gamma, \beta)$, unlike that in Drukker et al. (2013), our rank condition on $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ involves $\rho \in \boldsymbol{\rho}$. Assumption 8 in Drukker et al. (2013) is in terms of the minimum eigenvalue of a relevant matrix, while our corresponding condition (C.3) requires some matrices to have full rank in the limit, which seems to be more explicit. Furthermore, as $(\lambda, \gamma, \beta)$ is estimated jointly with $\rho$ in our approach, some of the parameters in $(\lambda, \gamma, \beta)$ can be identified from the quadratic moments, thus we have the identification condition in Assumption 6(ii).

While Assumption 6 guarantees $\lim _{n \rightarrow \infty} \mathrm{E}\left[g_{n}(\theta)\right]$ to be uniquely zero at $\theta=\theta_{0}$, it is necessary but may not be sufficient for $\lim _{n \rightarrow \infty} a_{n} \mathrm{E}\left[g_{n}(\theta)\right]$ to be uniquely zero at $\theta=\theta_{0}$. Note that the dimension of $a_{n}$ is $k_{a} \times k_{g}$, where $k_{a}$ can be smaller than $k_{g}$. For example, $\left[\kappa-\kappa_{0}, \tau-\tau_{0}\right]^{\prime}=0$
implies that $[\kappa, \tau]=\left[\kappa_{0}, \tau_{0}\right]$, but $\left(\kappa-\kappa_{0}\right)+\left(\tau-\tau_{0}\right)=0$ does not have the implication. If $\lim _{n \rightarrow \infty} a_{n}$ has full column rank, where $k_{a} \geq k_{g}$, then Assumption 6 is sufficient for $\lim _{n \rightarrow \infty} a_{n} \mathrm{E}\left[g_{n}(\theta)\right]$ to be uniquely zero at $\theta=\theta_{0}$. As we would like to consider a general class of GMM estimators with the weighting matrix $a_{n}^{\prime} a_{n}$ and investigate the optimal choice of $a_{n}^{\prime} a_{n}$ as in Hansen (1982), the following assumption is imposed.

Assumption 7. $\lim _{n \rightarrow \infty} a_{n} \mathrm{E}\left[g_{n}(\theta)\right]$ is uniquely zero at $\theta=\theta_{0}$.
The following assumption contains some technical conditions needed for the consistency of the GMM estimator $\hat{\theta}_{\text {GMM }}$.

Assumption 8. $\frac{1}{n} Q_{n}^{\prime} A_{n} \check{Z}_{n}=o_{p}(1)$, and for each $j=1, \ldots, m, \frac{1}{n} \Upsilon_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}=o_{p}(1)$, $\frac{1}{n} \check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}-\frac{1}{n} \mathrm{E}\left(\check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=o_{p}(1), \frac{1}{n} \epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}-\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=o_{p}(1)$, $\frac{1}{n} \mathrm{E}\left(\check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=O(1)$ and $\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=O(1)$, where $\Upsilon_{n}=\left[\Upsilon_{1 n}, M_{n} \Upsilon_{1 n}\right]$ with $\Upsilon_{1 n}=\left[T_{n} \bar{Z}_{n}, T_{n} X_{n}, \bar{Z}_{n}, X_{n}\right] ; A_{n}$ and $B_{n}$ are either $I_{n}, M_{n}, T_{n}$ or $M_{n} T_{n} ;$ and $C_{n}=I_{n}, H_{n}$, $T_{n} R_{n}^{-1}$ or $M_{n} T_{n} R_{n}^{-1}$.

If the endogenous regressors $Z_{n}$ have the reduced form (2), it is straightforward to verify Assumption 8. Since we do not assume a reduced form of $Z_{n}$, we impose the convergence and order conditions in Assumption 8. As mentioned above, we may allow for spatial dependence and heterogeneity in $Z_{n}$. In those situations, the conditions in the above assumption can be verified by the law of large numbers for spatial near-epoch processes, which are processes with weak spatial dependence developed by Jenish and Prucha (2012). Based on spatial near-epoch processes, the supplementary file of Jin and Lee (2018) provides some primitive conditions for orders of terms similar to those in the above assumption. Thus, we maintain the relatively high level assumption above for simplicity. The consistency of $\hat{\theta}_{\mathrm{GMM}}$ holds under the above assumptions.

Proposition 1. Under Assumptions 1-5 and 7-8, the GMM estimator $\hat{\theta}_{\mathrm{GMM}}$ is consistent.
As usual, to derive the asymptotic distribution of $\hat{\theta}_{\text {GMM }}$, we require $\theta_{0}$ to be in the interior $\operatorname{int}(\Theta)$ of the parameter space $\Theta$.

Assumption 9. $\theta_{0} \in \operatorname{int}(\Theta)$.
The variance matrix $\Omega_{n}$ of $\sqrt{n} g_{n}\left(\theta_{0}\right)$ can be derived by, e.g., Lemma 2 in Jin and Lee (2012) on the covariances of linear and quadratic forms. For any square matrix $A$, let $A^{s}=A+A^{\prime}, \operatorname{vec}(A)$ be the vectorization of $A$, and $d_{A}$ be a column vector formed by the diagonal elements of $A$. When $\epsilon_{n i}$ 's are i.i.d., $\Omega_{n}$ has the expression

$$
\Omega_{n}=\frac{1}{n}\left(\begin{array}{cc}
\left(\mu_{40}-3 \sigma_{0}^{4}\right) \omega_{n d}^{\prime} \omega_{n d}+\frac{\sigma_{0}^{4}}{2} \omega_{n}^{\prime} \omega_{n} & \mu_{30} \omega_{n d}^{\prime} Q_{n}  \tag{9}\\
\mu_{30} Q_{n}^{\prime} \omega_{n d} & \sigma_{0}^{2} Q_{n}^{\prime} Q_{n}
\end{array}\right)
$$

where $\mu_{30}=\mathrm{E}\left(\epsilon_{n i}^{3}\right), \mu_{40}=\mathrm{E}\left(\epsilon_{n i}^{4}\right), \omega_{n d}=\left[d_{P_{1 n}}, \cdots, d_{P_{k_{p} n}}\right]$, and $\omega_{n}=\left[\operatorname{vec}\left(P_{1 n}^{s}\right), \cdots, \operatorname{vec}\left(P_{k_{p} n}^{s}\right)\right]$; when $\epsilon_{n i}$ 's are heteroskedastic, as $P_{j n}$ 's have zero diagonals,

$$
\Omega_{n}=\frac{1}{n}\left(\begin{array}{cc}
\frac{1}{2} \omega_{n h}^{\prime} \omega_{n h} &  \tag{10}\\
& Q_{n}^{\prime} \Sigma_{n} Q_{n}
\end{array}\right)
$$

where $\omega_{n h}=\left[\operatorname{vec}\left(\Sigma_{n}^{1 / 2} P_{1 n}^{s} \Sigma_{n}^{1 / 2}\right), \cdots, \operatorname{vec}\left(\Sigma_{n}^{1 / 2} P_{k_{p} n}^{s} \Sigma_{n}^{1 / 2}\right)\right]$ with $\Sigma_{n}^{1 / 2}=\operatorname{diag}\left(\sigma_{n 1}, \ldots, \sigma_{n n}\right)$. As $\operatorname{tr}(A B)=$ $\operatorname{vec}^{\prime}\left(A^{\prime}\right) \operatorname{vec}(B)$ for two conformable square matrices $A$ and $B$, the $(j, k)$ th element of $\omega_{n}^{\prime} \omega_{n}$ is $\operatorname{tr}\left(P_{j n}^{s} P_{k n}^{s}\right)$, and the $(j, k)$ th element of $\omega_{n h}^{\prime} \omega_{n h}$ is $\operatorname{tr}\left(\Sigma_{n} P_{j n}^{s} \Sigma_{n} P_{k n}^{s}\right)$.

The gradient matrix $G_{n}=\mathrm{E}\left(\frac{\partial g_{n}\left(\theta_{0}\right)}{\partial \theta^{\prime}}\right)$ has the following expression:

$$
G_{n}=-\frac{1}{n}\left(\begin{array}{cccc}
\mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} R_{n} \zeta_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} H_{n} \epsilon_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} R_{n} \check{Z}_{n}\right) & 0  \tag{11}\\
\vdots & \vdots & \vdots & \vdots \\
\mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p n} n}^{s} R_{n} \zeta_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p} n}^{s} H_{n} \epsilon_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p} n}^{s} R_{n} \check{Z}_{n}\right) & 0 \\
Q_{n}^{\prime} R_{n} T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right) & 0 & Q_{n}^{\prime} R_{n} \bar{Z}_{n} & Q_{n}^{\prime} R_{n} X_{n}
\end{array}\right)
$$

where $\zeta_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right)$. For $\hat{\theta}_{\mathrm{GMM}}$ to be $\sqrt{n}$-consistent, $\lim _{n \rightarrow \infty} a_{n} G_{n}$ needs to have full column rank, for which a necessary condition is that $\lim _{n \rightarrow \infty} G_{n}$ has full column rank. The following Assumption 10 guarantees that $\lim _{n \rightarrow \infty} G_{n}$ has full column rank. Let

$$
G_{1 n}=-\frac{1}{n}\left(\begin{array}{ccc}
\mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} R_{n} \zeta_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} H_{n} \epsilon_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} R_{n} \check{Z}_{n}\right)  \tag{12}\\
\vdots & \vdots & \vdots \\
\mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p} n}^{s} R_{n} \zeta_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p} n}^{s} H_{n} \epsilon_{n}\right) & \mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p} n}^{s} R_{n} \check{Z}_{n}\right)
\end{array}\right)
$$

Assumption 10. In the case of Assumption $6(i), \lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n}^{s} H_{n} \epsilon_{n}\right) \neq 0$ for some $1 \leq j \leq$ $k_{p}$; in the case of Assumption $6(i i), \lim _{n \rightarrow \infty} G_{1 n}$ has full column rank.

In the case that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has full column rank for any $\rho \in \boldsymbol{\rho}$, which is a condition in Assumption 6(i), the above assumption excludes the second situation in (C.3), where each $\lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n}^{s} H_{n} \epsilon_{n}\right)$ is zero.

Proposition 2. Under Assumptions 1-5 and 7-9, if $\lim _{n \rightarrow \infty} a_{n} G_{n}$ has full column rank, the GMM estimator $\hat{\theta}_{\text {GMM }}$ has the asymptotic distribution

$$
\sqrt{n}\left(\hat{\theta}_{\mathrm{GMM}}-\theta_{0}\right) \xrightarrow{d} N\left(0, \lim _{n \rightarrow \infty}\left(G_{n}^{\prime} a_{n}^{\prime} a_{n} G_{n}\right)^{-1} G_{n}^{\prime} a_{n}^{\prime} a_{n} \Omega_{n} a_{n}^{\prime} a_{n} G_{n}\left(G_{n}^{\prime} a_{n}^{\prime} a_{n} G_{n}\right)^{-1}\right) .
$$

The gradient matrix $G_{n}$ in (11) involves the correlation between $\check{Z}_{n}$ and $\epsilon_{n}$ with an unknown form, thus the explicit expression of $G_{n}$ cannot be used to estimate $G_{n}$ using a plug-in approach. However, $G_{n}$ can be estimated by $\frac{\partial g_{n}\left(\hat{\theta}_{\mathrm{GMN}}\right)}{\partial \theta^{\prime}}$. Since each element of $g_{n}(\theta)$ is a polynomial function of $\theta$, by the proof of Proposition 2, $\frac{\partial g_{n}\left(\hat{\theta}_{\mathrm{GNM}}\right)}{\partial \theta^{\prime}}$ is a consistent estimator of $\lim _{n \rightarrow \infty} G_{n}$.

As in Hansen (1982), the optimal weighting matrix $a_{n}^{\prime} a_{n}$ is the matrix inverse $\Omega_{n}^{-1}$ of the variance matrix. To formulate an optimal GMM (OGMM) estimator, $\lim _{n \rightarrow \infty} \Omega_{n}$ needs to be invertible, which implies that $\Omega_{n}$ is also invertible for a large enough $n$. Let $\xi=\frac{\sqrt{2}}{2}\left(\frac{\mu_{40}}{\sigma_{0}^{4}}-1-\frac{\mu_{30}^{2}}{\sigma_{0}^{6}}\right)^{1 / 2}$, $P_{j n, \xi}^{s}=\xi \operatorname{diag}\left(P_{j n}^{s}\right)+\left[P_{j n}^{s}-\operatorname{diag}\left(P_{j n}^{s}\right)\right]$ and $\omega_{n \xi}=\left[\operatorname{vec}\left(P_{1 n, \xi}^{s}\right), \cdots, \operatorname{vec}\left(P_{k_{p} n, \xi}^{s}\right)\right] .{ }^{4}$ By Jin et al. (2020), $\Omega_{n}$ in (9) in the homoskedastic case can be rewritten as

$$
\Omega_{n}=\frac{1}{n}\left(\begin{array}{cc}
\frac{\mu_{30}^{2}}{\sigma_{0}^{2}} \omega_{n d}^{\prime} \omega_{n d}+\frac{\sigma_{0}^{4}}{2} \omega_{n \xi}^{\prime} \omega_{n \xi} & \mu_{30} \omega_{n d}^{\prime} Q_{n}  \tag{13}\\
\mu_{30} Q_{n}^{\prime} \omega_{n d} & \sigma_{0}^{2} Q_{n}^{\prime} Q_{n}
\end{array}\right) .
$$

Then the following assumption guarantees that $\lim _{n \rightarrow \infty} \Omega_{n}$ is positive definite.
Assumption 11. In the case of Assumption 1(a) with homoskedastic disturbances, $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} Q_{n}$ and $\lim _{n \rightarrow \infty} \frac{1}{n}\left\{\frac{2 \mu_{30}^{2}}{\sigma_{0}^{6}} \omega_{n d}^{\prime}\left[I_{n}-Q_{n}\left(Q_{n}^{\prime} Q_{n}\right)^{-1} Q_{n}^{\prime}\right] \omega_{n d}+\omega_{n \xi}^{\prime} \omega_{n \xi}\right\}$ are nonsingular; in the case of Assumption 1(b) with heteroskedastic disturbances, $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} \Sigma_{n} Q_{n}$ and $\lim _{n \rightarrow \infty} \frac{1}{n} \omega_{n h}^{\prime} \omega_{n h}$ are nonsingular.

For a block matrix $E=\left(\begin{array}{cc}A & B \\ C & D\end{array}\right)$, where $A$ and $D$ are square matrices, if $D$ is invertible, then

$$
\left(\begin{array}{cc}
I & -B D^{-1}  \tag{14}\\
0 & I
\end{array}\right)\left(\begin{array}{cc}
A & B \\
C & D
\end{array}\right)\left(\begin{array}{cc}
I & 0 \\
-D^{-1} C & I
\end{array}\right)=\left(\begin{array}{cc}
A-B D^{-1} C & 0 \\
0 & D
\end{array}\right) .
$$

Thus, if $D$ is invertible, then $E$ is invertible if and only if $A-B D^{-1} C$ is invertible. In Assumption 11, for the homoskedastic case, as the condition that $\lim _{n \rightarrow \infty} \Omega_{n}$ is positive definite implies that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} Q_{n}$ is nonsingular, we can see by (14) that the nonsingularity of $\lim _{n \rightarrow \infty} \frac{1}{n}\left\{\frac{2 \mu_{30}^{2}}{\sigma_{0}^{0}} \omega_{n d}^{\prime}\left[I_{n}-\right.\right.$ $\left.\left.Q_{n}\left(Q_{n}^{\prime} Q_{n}\right)^{-1} Q_{n}^{\prime}\right] \omega_{n d}+\omega_{n \xi}^{\prime} \omega_{n \xi}\right\}$ implies that of $\lim _{n \rightarrow \infty} \Omega_{n}$. Furthermore, (14) implies that the nonsingularity of $\lim _{n \rightarrow \infty} \frac{1}{n} \omega_{n d}^{\prime}\left[I_{n}-Q_{n}\left(Q_{n}^{\prime} Q_{n}\right)^{-1} Q_{n}^{\prime}\right] \omega_{n d}$ is guaranteed by that of $\lim _{n \rightarrow \infty} \frac{1}{n}\left[Q_{n}, \omega_{n d}\right]^{\prime}\left[Q_{n}, \omega_{n d}\right]$. Thus, in the homoskedastic case of Assumption 11, when $\mu_{30} \neq 0$, either $(i)$ the nonsingularity of $\lim _{n \rightarrow \infty} \frac{1}{n}\left[Q_{n}, \omega_{n d}\right]^{\prime}\left[Q_{n}, \omega_{n d}\right]$ or (ii) the nonsingularity of both $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} Q_{n}$ and $\lim _{n \rightarrow \infty} \frac{1}{n} \omega_{n \xi}^{\prime} \omega_{n \xi}$ guarantees the nonsingularity of $\lim _{n \rightarrow \infty} \Omega_{n}$; when $\mu_{30}=0,(i i)$ is required. In the heteroskedastic case, as $\Omega_{n}$ is block diagonal, the conditions in Assumption 11 are straightforward. By the definitions of $\omega_{n d}, \omega_{n \xi}$ and $\omega_{n h}$, if $P_{j n}$ 's are linearly dependent, then $\omega_{n d}, \omega_{n \xi}$ and $\omega_{n h}$ do not have full column rank and Assumption 11 is not satisfied. Thus $P_{j n}$ 's should be linearly independent under Assumption 11.

Let $\hat{\Omega}_{n}$ be a consistent estimator of $\lim _{n \rightarrow \infty} \Omega_{n}$. In the homoskedastic case, $\hat{\Omega}_{n}$ can be obtained by plugging consistent estimators of involved unknown parameters into $\Omega_{n}$; in the heteroskedastic case, as in the approach of White (1980), $\hat{\Omega}_{n}$ can be obtained by replacing each $\Sigma_{n}$ in $\Omega_{n}$ with the diagonal matrix $\hat{\Sigma}_{n}=\operatorname{diag}\left(\epsilon_{n 1}^{2}\left(\hat{\theta}_{\text {GMM }}\right), \ldots, \epsilon_{n n}^{2}\left(\hat{\theta}_{\text {GMM }}\right)\right)$, where $\epsilon_{n j}(\theta)$ is the $j$ th element of $\epsilon_{n}(\theta)$. Lin and Lee (2010) prove the consistency of a White-type variance estimator in the heteroskedastic case for

[^4]SAR models with no endogenous regressors. For SAR models with endogenous regressors, the proof is similar. With $\hat{\Omega}_{n}$, the feasible OGMM estimator $\hat{\theta}_{\text {OGMM }}$ is $\hat{\theta}_{\text {OGMM }}=\arg \min _{\theta \in \Theta} g_{n}^{\prime}(\theta) \hat{\Omega}_{n}^{-1} g_{n}(\theta)$. Under regularity conditions, $\hat{\theta}_{\text {OGMM }}$ is consistent and asymptotically normal, and its objective function can be used to test for over-identification.

Proposition 3. Under Assumptions 1-6 and 8-11, if $\hat{\Omega}_{n}=\Omega_{n}+o_{p}(1)$, the feasible OGMM estimator $\hat{\theta}_{\text {OGMM }}$ is consistent and follows the asymptotic distribution

$$
\sqrt{n}\left(\hat{\theta}_{\mathrm{OGMM}}-\theta_{0}\right) \xrightarrow{d} N\left(0, \lim _{n \rightarrow \infty}\left(G_{n}^{\prime} \Omega_{n}^{-1} G_{n}\right)^{-1}\right) .
$$

Besides, $n g_{n}^{\prime}\left(\hat{\theta}_{\text {OGMM }}\right) \hat{\Omega}_{n}^{-1} g_{n}\left(\hat{\theta}_{\text {OGMM }}\right) \xrightarrow{d} \chi^{2}\left(k_{g}-k_{\theta}\right)$.
Our results above are based on a given set of linear and quadratic moments. When disturbances are homoskedastic, there is an issue on the best selection of linear and quadratic moments (Liu et al., 2010). ${ }^{5}$ We use the analytical method in Jin et al. (2020) to derive the best linear and quadratic moments. In their method, the variance matrix $\Omega_{n}$ is rewritten in a form $\frac{1}{n} \Delta_{n}^{\prime} \Delta_{n}$ and the gradient matrix is rewritten in a form $-\frac{1}{n} \Delta_{n}^{\prime} \Gamma_{n}$, where $\Gamma_{n}$ is properly reformulated, so that the Cauchy-Schwarz inequality can be applied to derive a lower bound for the asymptotic variance $\left(G_{n}^{\prime} \Omega_{n}^{-1} G_{n}\right)^{-1}$ in Proposition 3 and the lower bound can be attained by using some IV matrix $Q_{n}$ and quadratic matrices $P_{j n}$ 's. Let $\Psi_{n}=R_{n} T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), l_{n}$ be an $n \times 1$ vector of ones, $\tilde{a}_{n}=a_{n}-\frac{1}{n} l_{n} l_{n}^{\prime} a_{n}$ for any $n \times 1$ vector $a_{n}, B_{n, j}$ be the $j$ th column of an $n \times k_{b}$ matrix $B_{n}$, $C_{1 n}=R_{n} \mathrm{E}\left(\zeta_{n} \epsilon_{n}^{\prime}\right)-I_{n} \operatorname{tr}\left[R_{n} \mathrm{E}\left(\zeta_{n} \epsilon_{n}^{\prime}\right)\right] / n, C_{2 n}=H_{n}-I_{n} \operatorname{tr}\left(H_{n}\right) / n$, and $C_{2+j, n}=R_{n} \mathrm{E}\left(\check{Z}_{n, j} \epsilon_{n}^{\prime}\right)-$ $I_{n} \operatorname{tr}\left[R_{n} \mathrm{E}\left(\check{Z}_{n, \cdot j} \epsilon_{n}^{\prime}\right)\right] / n$ for $j=1, \ldots, k_{z}$. Note that the sum of all elements in $\tilde{a}_{n}$ is zero, and $C_{j n}$ 's have zero traces.

Proposition 4. Suppose that Assumptions 1(a), 2-6 and 8-11 are satisfied.
(a) The best $Q_{n}$ and $P_{j n}$ 's that can generate an OGMM estimator with the minimum asymptotic variance are

$$
\begin{aligned}
Q_{n}^{*}= & {\left[\Psi_{n}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{C_{1 n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \tilde{\Psi}_{n}, d_{C_{2 n}},\right.} \\
& R_{n} \bar{Z}_{n, 1}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{C_{3 n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} \bar{Z}_{n, 1},}, \cdots, R_{n} \bar{Z}_{n, k_{z}}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{C_{k_{z}+2, n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} \bar{Z}_{n, k_{z}}}, \\
& \left.R_{n} X_{n, 1}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} X_{n, 1}}, \cdots, R_{n} X_{n, k_{x}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} X_{n, \cdot k_{x}}}\right],
\end{aligned}
$$

[^5]\[

$$
\begin{aligned}
& P_{1 n}^{*}=\left[C_{1 n}-\operatorname{diag}\left(C_{1 n}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(C_{1 n}\right)-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{\Psi}_{n}\right), P_{2 n}^{*}=\left[C_{2 n}-\operatorname{diag}\left(C_{2 n}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(C_{2 n}\right), \\
& P_{2+j, n}^{*}=\left[C_{2+j, n}-\operatorname{diag}\left(C_{2+j, n}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(C_{2+j, n}\right)-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\widetilde{R_{n} \bar{Z}_{n, j}}\right) \text { for } j=1, \ldots, k_{z}, \text { and } \\
& P_{2+k_{z}+j, n}^{*}=\operatorname{diag}\left(\widetilde{R_{n} X_{n, j}}\right) \text { for } j=1, \ldots, k_{x} .
\end{aligned}
$$
\]

(b) The OGMM estimator with the above $Q_{n}^{*}$ and $P_{j n}^{*}$ 's, ${ }^{6}$ denoted by $\hat{\theta}_{\text {ВGMM }}$, has the asymptotic distribution $\sqrt{n}\left(\hat{\theta}_{\mathrm{BGMM}}-\theta_{0}\right) \xrightarrow{d} N\left(0, \lim _{n \rightarrow \infty}\left(\frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}\right)^{-1}\right)$, where

$$
\Gamma_{n}=\left(\begin{array}{cc}
\Gamma_{n, 11} & -\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}}\left[\operatorname{vec}\left(\operatorname{diag}\left(\widetilde{R_{n} X_{n, 1}}\right)\right), \cdots, \operatorname{vec}\left(\operatorname{diag}\left(\widetilde{R_{n} X_{n, k_{x}}}\right)\right)\right] \\
\frac{1}{\sigma_{0}}\left[\Psi_{n}, 0_{n \times 1}, R_{n} \bar{Z}_{n}\right] & \frac{1}{\sigma_{0}} R_{n} X_{n}
\end{array}\right)
$$

with

$$
\begin{aligned}
\Gamma_{n, 11}= & \frac{1}{\sqrt{2} \sigma_{0}^{2}}\left[\operatorname{vec}\left(C_{1 n, 1 / \xi}^{s}-\frac{\mu_{30}}{\xi \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{\Psi}_{n}\right)\right), \operatorname{vec}\left(C_{2 n, 1 / \xi}^{s}\right)\right. \\
& \left.\quad \operatorname{vec}\left(C_{3 n, 1 / \xi}^{s}-\frac{\mu_{30}}{\xi \sigma_{0}^{2}} \operatorname{diag}\left(\widetilde{R_{n} \bar{Z}_{n, 1}}\right)\right), \cdots, \operatorname{vec}\left(C_{k_{z}+2, n, 1 / \xi}^{s}-\frac{\mu_{30}}{\xi \sigma_{0}^{2}} \operatorname{diag}\left(\widetilde{R_{n} \bar{Z}_{n, k_{z}}}\right)\right)\right]
\end{aligned}
$$

(c) When $\mu_{30}=0$, the $I V d_{C_{2 n}}$ is redundant and the quadratic matrices $\operatorname{diag}\left(\widetilde{R_{n} X_{n, j}}\right)$ for $j=$ $1, \ldots, k_{x}$ are redundant, so $Q_{n}^{*}$ reduces to $Q_{n}^{*}=\left[\Psi_{n}, R_{n} \bar{Z}_{n}, R_{n} X_{n}\right]$ and $P_{j n}^{*}$ 's are $P_{j n}^{*}=$ $\left[C_{j n}-\operatorname{diag}\left(C_{j n}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(C_{j n}\right)$ for $j=1, \ldots, k_{z}+2$.
(d) For $Q_{n}^{*}$ and $P_{j n}^{*}$ 's in (a), if we use the IVs in each column of $Q_{n}^{*}$ and the quadratic matrices in each $P_{j n}^{*}$ separately, then $Q_{n}^{*}=\left[\Psi_{n}, R_{n} \bar{Z}_{n}, R_{n} X_{n}, d_{C_{1 n}}, \cdots, d_{C_{k_{z}+2, n}}, l_{n}\right],{ }^{7}$ and $P_{j n}^{*}$ 's are $C_{j n}-\operatorname{diag}\left(C_{j n}\right)$ for $j=1, \ldots, k_{z}+2, \operatorname{diag}\left(C_{j n}\right)$ for $j=1, \ldots, k_{z}+2, \operatorname{diag}\left(\tilde{\Psi}_{n}\right), \operatorname{diag}\left(\widetilde{R_{n} \bar{Z}_{n, j}}\right)$ for $j=1, \ldots, k_{z}$, and $\operatorname{diag}\left(\widetilde{R_{n} X_{n, j}}\right)$ for $j=1, \ldots, k_{x}$.
When $\mu_{30}=0, Q_{n}^{*}=\left[\Psi_{n}, R_{n} \bar{Z}_{n}, R_{n} X_{n}\right]$, and $P_{j n}^{*}$ 's are $P_{j n}^{*}=C_{j n}-\operatorname{diag}\left(C_{j n}\right)$ for $j=$ $1, \ldots, k_{z}+2$, and $P_{k_{z}+2+j, n}^{*}=\operatorname{diag}\left(C_{j n}\right)$ for $j=1, \ldots, k_{z}+2$.

Proposition $4(a)$ gives the best combined IVs and quadratic matrices, and Proposition $4(b)$ provides the corresponding asymptotic distribution. Note that the asymptotic variance is given by $\left(\frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}\right)^{-1}$ and we do not need to compute it with the sandwich form $\left(G_{n}^{\prime} \Omega_{n}^{-1} G_{n}\right)^{-1}$ as in Proposition 3. The combined IVs and quadratic matrices in Proposition 4(a) are more complicated than those separate IVs and quadratic matrices in Proposition 4(d), but they avoid the use of more moments. Generally, the presence of endogenous regressors $Z_{n}$ affects both the best IV matrix

[^6]$Q_{n}^{*}$ and the best quadratic matrices $P_{j n}^{*}$ 's. But when $\mu_{30}=0$, the endogeneity of $Z_{n}$, i.e., the correlation between $\check{Z}_{n}$ and $\epsilon_{n}$, does not affect the best IV matrix $Q_{n}^{*}$, although it affects the best quadratic matrices. While $\bar{Z}_{n}$ and the correlation between $\check{Z}_{n}$ and $\epsilon_{n}$ are unknown, we can choose IVs and quadratic moments according to the implications of the above proposition. If we have an IV matrix $F_{n}$ for $Z_{n}$, the 2SLS estimate of $Z_{n}$ is $\hat{Z}_{n}=F_{n}\left(F_{n}^{\prime} F_{n}\right)^{-1} F_{n}^{\prime} Z_{n}$, which is an estimate of $\bar{Z}_{n}$. By Proposition $4(a)$, as $\zeta_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right)$ and $\Psi_{n}=R_{n} T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), P_{j n}$ 's can be taken as
\[

$$
\begin{align*}
& \sigma_{0}^{2}\left[R_{n} T_{n} R_{n}^{-1}-\operatorname{diag}\left(R_{n} T_{n} R_{n}^{-1}\right)\right]+\frac{\sigma_{0}^{2}}{\xi^{2}} \operatorname{diag}\left(R_{n} T_{n} R_{n}^{-1}-\frac{\operatorname{tr}\left(T_{n}\right)}{n} I_{n}\right)-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{\Pi}_{n}\right), \\
& H_{n}-\operatorname{diag}\left(H_{n}\right)+\frac{1}{\xi^{2}} \operatorname{diag}\left(H_{n}-\frac{\operatorname{tr}\left(H_{n}\right)}{n} I_{n}\right), \operatorname{diag}\left(\widetilde{R_{n} \hat{Z}_{n,-1}}\right), \cdots, \operatorname{diag}\left(\widetilde{R_{n} \hat{Z}_{n, \cdot k_{z}}}\right)  \tag{15}\\
& \operatorname{diag}\left(\widetilde{\left(R_{n} X_{n, \cdot 1}\right.}\right), \cdots, \operatorname{diag}\left(\widetilde{R_{n} X_{n, k_{x}}}\right),
\end{align*}
$$
\]

where $\Pi_{n}=R_{n} T_{n}\left(\hat{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right)$, and the IV matrix $Q_{n}$ can be taken as

$$
\begin{align*}
& {\left[\Pi_{n}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{2}} d_{R_{n} T_{n} R_{n}^{-1}-I_{n} \operatorname{tr}\left(T_{n}\right) / n}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \tilde{\Pi}_{n}, d_{H_{n}-I_{n} \operatorname{tr}\left(H_{n}\right) / n}\right.} \\
& \quad R_{n} \hat{Z}_{n, 1}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} \hat{Z}_{n, \cdot 1}}, \cdots, R_{n} \hat{Z}_{n, k_{z}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} \hat{Z}_{n, k_{z}}}  \tag{16}\\
& \left.\quad R_{n} X_{n, \cdot 1}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} X_{n, \cdot 1}}, \cdots, R_{n} X_{n, k_{x}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{R_{n} X_{n, k_{x}}}\right]
\end{align*}
$$

When $\mu_{30}=0$, the quadratic matrices $\operatorname{diag}\left(\widetilde{R_{n} \hat{Z}_{n,-1}}\right), \ldots, \operatorname{diag}\left(\widetilde{R_{n} \hat{Z}_{n, k_{z}}}\right), \operatorname{diag}\left(\widetilde{R_{n} X_{n,-1}}\right), \ldots, \operatorname{diag}\left(\widetilde{R_{n} X_{n, k_{x}}}\right)$ in (15) are redundant, and the IV $d_{H_{n}-I_{n} \operatorname{tr}\left(H_{n}\right) / n}$ in (16) is redundant. The unknown parameters in $P_{j n}$ 's and $Q_{n}$ can be replaced by their consistent estimators, which will not affect the asymptotic distribution of the corresponding OGMM estimator, as in Liu et al. (2010) for SAR models without endogenous regressors.

Model (1) nests the special case of an SARAR model with no endogenous regressors, for which the best IV matrix $Q_{n}$ and the best $P_{j n}$ 's can be deduced from Proposition 4. We can see that the results are the same as those in Lee and Liu (2010) for the SARAR model. Another special model of interest nested in model (1) is the SAR model with endogenous regressors and without SAR disturbances. We present the best linear and quadratic moments for such a model in Appendix B.

Note that $\xi=1$ when $\mu_{30}=0$ and $\mu_{40}=3 \sigma_{0}^{4}$, e.g., when $\epsilon_{n i}$ 's are normally distributed. In such a situation, by Proposition $4(c), Q_{n}^{*}=\left[\Psi_{n}, R_{n} \bar{Z}_{n}, R_{n} X_{n}\right]$ and $P_{j n}^{*}$ 's are $P_{j n}^{*}=C_{j n}$ for $j=1, \ldots, k_{z}+2$.

## 3 Monte Carlo

In this section, we conduct some Monte Carlo experiments to study the finite sample performance of the proposed GMM estimators.

We first generate data from model (1) with no SAR process on disturbances and with one endogenous regressor in $Z_{n}$, i.e.,

$$
\begin{equation*}
Y_{n}=\lambda W_{n} Y_{n}+Z_{n} \gamma+X_{n} \beta+\epsilon_{n} \tag{17}
\end{equation*}
$$

where elements $\epsilon_{n i}$ 's of $\epsilon_{n}$ are independent, $W_{n}$ is a block diagonal matrix with each block being a row-normalized matrix for the study in Anselin (1988) on crime activities in 49 districts of Columbus, $\mathrm{OH}, X_{n}$ contains a variable randomly drawn from the standard normal distribution, $\lambda_{0}=0.5, \gamma_{0}=1$, and $\beta_{0}=1$. The endogenous regressor $Z_{n}$ in (17) is generated from the following model:

$$
\begin{equation*}
Z_{n}=\kappa W_{n} Z_{n}+F_{n} \delta+v_{n}, \tag{18}
\end{equation*}
$$

where $F_{n}$ and $v_{n}=\left[v_{n 1}, \ldots, v_{n n}\right]^{\prime}$ are independent, elements of $F_{n}$ and $v_{n}$ are random draws from the standard normal distribution, $\delta=1$, and $\kappa$ is either 0 or 0.5 . Each element $\epsilon_{n i}$ of $\epsilon_{n}$ in (17) is equal to $\frac{1}{2} v_{n i}+\frac{\sqrt{3}}{2} \tau_{n i}$, where $\tau_{n i}$ 's in the homoskedastic case are randomly drawn from either the standard normal distribution or the gamma $(1,1)$ distribution with its mean adjusted to be zero, which has unit variance, skewness 2 and excess kurtosis 6 ; and $\tau_{n i}$ 's in the heteroskedastic case are further multiplied by $\sqrt{c_{n i}}$, where $c_{n i}$ is proportional to the number of nonzero elements in the $i$ th row of $W_{n}$ and the mean of $c_{n i}$ 's is 1 . Thus, the mean of $\epsilon_{n i}$ 's variances is 1 .

We consider three OGMM estimators in the homoskedastic case: the first estimator BGMM is the theoretically best GMM estimator with linear and quadratic moments, with moments given in Corollary $1(a)$; for the second estimator GMM2, the IV matrix is $\left[X_{n}, F_{n}, W_{n} X_{n}, W_{n} F_{n}, W_{n}^{2} X_{n}, W_{n}^{2} F_{n}\right]$, and the quadratic moments have square matrices $W_{n}$ and $W_{n}^{2}-I_{n} \operatorname{tr}\left(W_{n}^{2}\right) / n$; and for the third estimator GMM3, the square matrices for quadratic moments and the IV matrix are in, respectively, (B.2) and (B.3), which are implied from the theoretically best $P_{j n}$ 's and $Q_{n}$. In the first steps of BGMM, GMM2 and GMM3, identity matrices are used as weighting matrices in the GMM objective functions. BGMM provides a basis for comparisons. For GMM3, the unknown parameters in $Q_{n}$ and $P_{j n}$ 's are replaced by their first step estimates for GMM2, and the redundant IVs and quadratic matrices in the case of normally distributed $\tau_{n i}$ 's are excluded. In the heteroskedastic case, the quadratic moments with diagonal quadratic matrices are removed, and the quadratic matrices for other quadratic moments are modified to have zero diagonals. Corresponding to GMM2, the GMM estimator in Liu and Saraiva (2015) with the same IV matrix and quadratic matrices is computed for comparison purposes, which is denoted by GMM2-LS. The moment conditions in Liu and Saraiva (2015) at true parameters are linear and quadratic in $\epsilon_{n}$ and $v_{n}$, so there are 2 linear moments corresponding to each IV and 4 quadratic moments corresponding to each quadratic matrix. We also report results on the 2SLS estimator, for which the IV matrix is the same as that for GMM2. The sample size is either 196 or 392, and the number of Monte Carlo repetitions is 5, 000 .

Table 1 reports the estimation results for the case with homoskedastic disturbances $\epsilon_{n i}$ 's. Note that GMM2-LS is consistent when $\kappa=0$, but it is not when $\kappa=0.5$. We observe that all estimators have relatively small biases when $\kappa=0$, but GMM2-LS has relatively large biases when $\kappa=0.5$ and the biases do not decrease as the sample size doubles from 196 to 392, while other estimators still have small biases for the case with $\kappa=0.5$. When $\tau_{n i}$ 's are normally distributed, BGMM, GMM2 and GMM3 have similar standard deviations (SD); when $\tau_{n i}$ 's are gamma-distributed, BGMM and GMM3 have similar SDs, which are smaller than those of GMM2. In particular, with gamma-distributed $\tau_{n i}$ 's, BGMM and GMM3 show very significant efficiency improvement upon GMM2 for the parameters $\gamma$ and $\beta$. For all estimators, as the SDs dominate biases, the root mean squared errors (RMSE) are similar to the SDs. For the case with $\kappa=0$, GMM2-LS does not always have smaller SDs and RMSEs than GMM2. This is the case since GMM2-LS also estimates the parameter $\kappa$ in the reduced form of $Z_{n}$, although GMM2-LS employs more moment conditions. 2SLS has significantly larger SDs for the spatial dependence parameter than other estimators. It also has the largest SD for $\beta$, and the second largest SDs for $\gamma$, which are only smaller than those of GMM2-LS. As the sample size increases from $n=196$ to $n=392$, the SDs and RMSEs of BGMM, GMM2 and GMM3 decrease.

Table 2 reports the estimation results for the case with heteroskedastic disturbances. GMM2LS still has relatively small biases when $\kappa=0$ and relatively large biases when $\kappa=0.5$, while other estimators have smaller biases for both $\kappa=0$ and $\kappa=0.5$. BGMM, GMM2 and GMM3 have similar SDs and RMSEs. ${ }^{8}$ The patterns for the performance of 2SLS are similar to those in the homoskedastic case.

We also generate data from model (1), where the spatial weights matrix $M_{n}$ is based on the queen criterion and normalized to have row sums equal to one, the true $\rho_{0}$ is 0.2 , and other settings are the same as those for model (17). For the theoretically best GMM estimator BGMM with linear and quadratic moments in the homoskedastic case, the moments are given in Proposition 4. For the second estimator GMM2, the IV matrix is $\left[X_{n}, F_{n}, W_{n} X_{n}, W_{n} F_{n}, W_{n}^{2} X_{n}, W_{n}^{2} F_{n}\right.$ ], and the quadratic moments have square matrices $W_{n}, W_{n}^{2}-I_{n} \operatorname{tr}\left(W_{n}^{2}\right) / n, M_{n}$ and $M_{n}^{2}-I_{n} \operatorname{tr}\left(M_{n}^{2}\right) / n$. For the third estimator GMM3, the square matrices for quadratic moments and the IV matrix are in, respectively, (15) and (16), and the involved unknown parameters in the square matrices and IV matrix are replaced by their first step estimates for GMM2. GMM2-LS is not considered since it has not taken into account the SAR process in disturbances and thus it is not expected to perform well. The GS2SLS estimator in Drukker et al. (2013) is also considered, which uses

[^7]Table 1: Estimation results of model (17) with homoskedastic disturbances

|  |  | $\lambda$ | $\gamma$ | $\beta$ |
| :---: | :---: | :---: | :---: | :---: |
| $n=196$ |  |  |  |  |
| Normally distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0$ | BGMM | -0.002[0.042]0.042 | -0.002[0.072]0.072 | -0.003[0.071]0.071 |
|  | GMM2 | $0.003[0.042] 0.042$ | $0.010[0.070] 0.071$ | -0.004[0.071]0.071 |
|  | GMM2-LS | $0.004[0.038] 0.039$ | $-0.006[0.075] 0.075$ | -0.002[0.062]0.062 |
|  | GMM3 | -0.002[0.042]0.042 | -0.002[0.072]0.072 | -0.003[0.071]0.071 |
|  | 2SLS | $0.003[0.072] 0.073$ | $0.002[0.072] 0.072$ | -0.004[0.072]0.072 |
| Normally distributed $\tau_{n i}$ 's, $\kappa=0.5$ | BGMM | 0.001[0.037]0.037 | $-0.000[0.071] 0.071$ | -0.002[0.073]0.073 |
|  | GMM2 | $0.000[0.038] 0.038$ | $0.006[0.070] 0.070$ | -0.002[0.072]0.072 |
|  | GMM2-LS | -0.065[0.038]0.075 | 0.048 [0.079]0.092 | 0.011[0.065]0.066 |
|  | GMM3 | -0.000[0.038]0.038 | -0.003[0.073]0.073 | -0.003[0.072]0.072 |
|  | 2SLS | $0.000[0.062] 0.062$ | -0.000[0.074]0.074 | -0.002[0.073]0.073 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0$ | BGMM | -0.001[0.039]0.039 | $-0.003[0.062] 0.062$ | -0.002[0.060]0.060 |
|  | GMM2 | $0.002[0.042] 0.042$ | $0.009[0.072] 0.073$ | -0.003[0.073]0.073 |
|  | GMM2-LS | $0.003[0.039] 0.039$ | $-0.007[0.077] 0.077$ | -0.002[0.063]0.063 |
|  | GMM3 | -0.001[0.040]0.040 | -0.003[0.062]0.062 | -0.002[0.060]0.060 |
|  | 2SLS | $0.002[0.075] 0.075$ | $0.002[0.074] 0.074$ | $-0.003[0.074] 0.074$ |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | -0.002[0.035]0.035 | $-0.001[0.060] 0.060$ | -0.003[0.061]0.061 |
|  | GMM2 | -0.000[0.038]0.038 | $0.008[0.071] 0.071$ | -0.003[0.073]0.073 |
|  | GMM2-LS | -0.066[0.039]0.077 | $0.051[0.080] 0.094$ | 0.011[0.066]0.067 |
|  | GMM3 | -0.001[0.036]0.036 | $-0.001[0.061] 0.061$ | -0.003[0.061]0.061 |
|  | 2SLS | $0.000[0.061] 0.061$ | $0.002[0.074] 0.074$ | -0.003[0.074]0.074 |
| $n=392$ |  |  |  |  |
| Normally distributed $\tau_{n i}$ 's, $\kappa=0$ | BGMM | -0.001[0.029]0.029 | $-0.001[0.050] 0.050$ | -0.002[0.051]0.051 |
|  | GMM2 | $0.002[0.029] 0.029$ | $0.005[0.050] 0.050$ | -0.002[0.051]0.051 |
|  | GMM2-LS | $0.002[0.026] 0.026$ | -0.003[0.051]0.051 | -0.001[0.044]0.044 |
|  | GMM3 | -0.001[0.028]0.028 | -0.001[0.050]0.050 | -0.002[0.051]0.051 |
|  | 2SLS | $0.002[0.051] 0.051$ | $0.001[0.051] 0.051$ | -0.002[0.052]0.052 |
| Normally distributed $\tau_{n i}$ 's, $\kappa=0.5$ | BGMM | -0.000[0.026]0.026 | $0.000[0.050] 0.050$ | -0.002[0.051]0.051 |
|  | GMM2 | -0.001[0.026]0.026 | $0.003[0.050] 0.050$ | -0.002[0.051]0.051 |
|  | GMM2-LS | -0.066[0.027]0.071 | $0.052[0.056] 0.076$ | $0.011[0.046] 0.047$ |
|  | GMM3 | -0.001[0.026]0.026 | $-0.002[0.051] 0.051$ | -0.002[0.051]0.051 |
|  | 2SLS | -0.001[0.043]0.043 | $0.000[0.053] 0.053$ | -0.002[0.051]0.051 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0$ | BGMM | -0.001[0.027]0.027 | -0.001[0.043]0.043 | -0.001[0.043]0.043 |
|  | GMM2 | $0.001[0.029] 0.029$ | $0.004[0.051] 0.051$ | -0.001[0.052]0.052 |
|  | GMM2-LS | $0.001[0.026] 0.026$ | -0.004[0.052]0.053 | -0.001[0.045]0.045 |
|  | GMM3 | -0.001[0.027]0.027 | -0.001[0.043]0.043 | -0.001[0.043]0.043 |
|  | 2SLS | $0.001[0.050] 0.050$ | $0.001[0.052] 0.052$ | -0.001[0.052]0.052 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0.5$ | BGMM | -0.001[0.024]0.024 | -0.002[0.042]0.042 | -0.000[0.043]0.043 |
|  | GMM2 | -0.001[0.027]0.027 | $0.004[0.050] 0.050$ | -0.002[0.051]0.051 |
|  | GMM2-LS | -0.067[0.027]0.072 | $0.052[0.056] 0.077$ | 0.012[0.046]0.048 |
|  | GMM3 | -0.001[0.024]0.024 | -0.002[0.042]0.042 | -0.001[0.043]0.043 |
|  | 2SLS | -0.001[0.044]0.044 | 0.001[0.052]0.052 | -0.001[0.051]0.051 |

The three numbers in each cell are bias[SD]RMSE. $\left[\lambda_{0}, \gamma_{0}, \beta_{0}\right]=[0.5,1,1]$.

Table 2: Estimation results of model (17) with heteroskedastic disturbances

|  |  | $\lambda$ | $\gamma$ | $\beta$ |
| :---: | :---: | :---: | :---: | :---: |
| $n=196$ |  |  |  |  |
| Normally distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0$ | BGMM | -0.002[0.041]0.041 | -0.002[0.072]0.072 | $-0.003[0.073] 0.074$ |
|  | GMM2 | $0.003[0.041] 0.041$ | $0.010[0.071] 0.072$ | -0.003[0.074]0.074 |
|  | GMM2-LS | $0.004[0.036] 0.036$ | $-0.006[0.074] 0.074$ | -0.003[0.064]0.064 |
|  | GMM3 | -0.002[0.040]0.040 | $-0.002[0.072] 0.072$ | -0.003[0.073]0.073 |
|  | 2SLS | $0.003[0.070] 0.070$ | $0.002[0.072] 0.072$ | -0.003[0.073]0.074 |
| Normally distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | 0.000[0.036] 0.036 | $0.001[0.071] 0.071$ | -0.002[0.072]0.072 |
|  | GMM2 | -0.000[0.036]0.036 | $0.008[0.071] 0.071$ | -0.002[0.073]0.073 |
|  | GMM2-LS | -0.064[0.036]0.074 | $0.046[0.080] 0.093$ | $0.012[0.065] 0.067$ |
|  | GMM3 | -0.001[0.036]0.036 | $-0.002[0.072] 0.072$ | -0.002[0.072]0.072 |
|  | 2SLS | -0.000[0.058]0.058 | $0.001[0.074] 0.074$ | -0.001[0.073]0.073 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0$ | BGMM | -0.002[0.039]0.039 | -0.002[0.073]0.073 | -0.004[0.072]0.072 |
|  | GMM2 | $0.002[0.040] 0.040$ | $0.010[0.071] 0.072$ | -0.004[0.071]0.071 |
|  | GMM2-LS | $0.003[0.035] 0.035$ | -0.007[0.076]0.076 | -0.003[0.063]0.063 |
|  | GMM3 | -0.002[0.039]0.039 | -0.002[0.073]0.073 | -0.004[0.072]0.072 |
|  | 2SLS | 0.004[0.069]0.069 | $0.002[0.073] 0.073$ | $-0.005[0.072] 0.073$ |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | -0.000[0.036]0.036 | $0.001[0.070] 0.070$ | -0.004[0.073]0.073 |
|  | GMM2 | -0.001[0.036]0.036 | $0.008[0.070] 0.070$ | -0.004[0.072]0.072 |
|  | GMM2-LS | -0.064[0.037]0.074 | $0.046[0.080] 0.092$ | $0.009[0.066] 0.067$ |
|  | GMM3 | -0.001[0.036]0.036 | $-0.002[0.072] 0.072$ | -0.004[0.072]0.072 |
|  | 2SLS | -0.000[0.059]0.059 | $0.001[0.074] 0.074$ | -0.004[0.073]0.073 |
| $n=392$ |  |  |  |  |
| Normally distributed $\tau_{n i}$ 's, $\kappa=0$ | BGMM | -0.001[0.028]0.028 | $-0.001[0.051] 0.051$ | -0.002[0.050]0.050 |
|  | GMM2 | $0.002[0.028] 0.028$ | $0.005[0.051] 0.051$ | -0.002[0.050]0.050 |
|  | GMM2-LS | $0.002[0.025] 0.025$ | -0.004[0.052]0.052 | -0.001[0.044]0.044 |
|  | GMM3 | -0.001[0.028]0.028 | -0.001[0.051]0.051 | -0.002[0.050]0.050 |
|  | 2SLS | $0.002[0.048] 0.048$ | $0.001[0.051] 0.051$ | -0.002[0.051]0.051 |
| Normally distributed $\tau_{n i}{ }^{\text {'s }}$, $\kappa=0.5$ | BGMM | $0.000[0.025] 0.025$ | $0.001[0.050] 0.050$ | -0.001[0.051]0.051 |
|  | GMM2 | -0.000[0.025]0.025 | $0.004[0.050] 0.050$ | -0.001[0.052]0.052 |
|  | GMM2-LS | -0.065[0.026]0.070 | $0.050[0.057] 0.076$ | $0.013[0.046] 0.048$ |
|  | GMM3 | -0.000[0.025]0.025 | -0.001[0.051]0.051 | -0.001[0.051]0.051 |
|  | 2SLS | -0.000[0.041] 0.041 | $0.001[0.052] 0.052$ | -0.001[0.051]0.051 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0$ | BGMM | -0.001[0.028]0.028 | $0.001[0.051] 0.051$ | -0.002[0.052]0.052 |
|  | GMM2 | $0.001[0.028] 0.028$ | $0.007[0.050] 0.051$ | -0.002[0.051]0.051 |
|  | GMM2-LS | $0.002[0.025] 0.025$ | -0.002[0.052]0.052 | -0.001[0.045]0.045 |
|  | GMM3 | -0.001[0.028]0.028 | $0.001[0.051] 0.051$ | -0.002[0.051]0.051 |
|  | 2SLS | $0.001[0.048] 0.048$ | $0.003[0.051] 0.051$ | -0.002[0.052]0.052 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ s, $\kappa=0.5$ | BGMM | -0.000[0.025]0.025 | -0.001[0.050]0.050 | -0.002[0.050]0.050 |
|  | GMM2 | -0.001[0.026]0.026 | 0.003[0.049]0.049 | -0.002[0.050]0.050 |
|  | GMM2-LS | -0.065[0.026]0.070 | 0.047[0.057]0.075 | 0.012[0.045]0.047 |
|  | GMM3 | -0.001[0.025]0.025 | -0.002[0.051]0.051 | -0.002[0.050]0.050 |
|  | 2SLS | $0.000[0.040] 0.040$ | -0.001[0.052]0.052 | -0.002[0.050]0.050 |

The three numbers in each cell are bias[SD]RMSE. $\left[\lambda_{0}, \gamma_{0}, \beta_{0}\right]=[0.5,1,1]$.
the same quadratic moments as those of GMM2 in estimating the spatial dependence parameter in disturbances. It corresponds to the 2SLS estimator for model (17). Tables 3-4 report the estimation results in the homoskedastic and heteroskedastic cases respectively. We observe similar patterns for BGMM, GMM2 and GMM3 as those in Tables 1-2 for model (17). GS2SLS is observed to have the largest SDs and RMSEs.

In sum, our proposed GMM estimators perform well in finite samples for both homoskedastic and heteroskedastic cases, while the 2SLS or GS2SLS estimator has larger SDs and RMSEs, and the GMM estimator in Liu and Saraiva (2015) can have a bad performance if the endogenous regressors have a reduced form different from the assumed one. In the homoskedastic case, the feasible moments implied by the theoretically best linear and quadratic moments can generate a GMM estimator that has similar performance to that of the theoretically best GMM estimator. When the disturbances follow a distribution with nonzero skew and nonzero excess kurtosis, this feasible best GMM estimator can have significant efficiency improvement upon the GMM estimator with some linear and quadratic moments that are commonly used in the literature. We thus suggest the use of this feasible best GMM estimator in practice.

## 4 Conclusion

This paper considers the GMM estimation of SAR models with SAR disturbances and endogenous regressors. We do not assume any reduced form of the endogenous regressors, thus we allow for spatial dependence and heterogeneity in endogenous regressors, and also allow for nonlinear relations among endogenous regressors and their instruments. Both linear and quadratic moments are employed for estimation. We prove that GMM estimators are consistent and asymptotically normal in both the homoskedastic and heteroskedastic cases. In the homoskedastic case, we derive the best linear and quadratic moments that can generate an OGMM estimator with the minimum asymptotic variance.

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## Appendix A List of notations

$I_{n}$ is the $n \times n$ identity matrix, $S_{n}(\lambda)=I_{n}-\lambda W_{n}, R_{n}(\rho)=I_{n}-\rho M_{n}, S_{n}=S_{n}\left(\lambda_{0}\right), R_{n}=R_{n}\left(\rho_{0}\right)$, $\bar{Z}_{n}=\mathrm{E}\left(Z_{n}\right), \check{Z}_{n}=Z_{n}-\bar{Z}_{n}, T_{n}=W_{n} S_{n}^{-1}, H_{n}=M_{n} R_{n}^{-1}, \Omega_{n}=\operatorname{var}\left[\sqrt{n} g_{n}\left(\theta_{0}\right)\right]$ and $G_{n}=\mathrm{E}\left(\frac{\partial g_{n}\left(\theta_{0}\right)}{\partial \theta^{\prime}}\right)$.

Table 3: Estimation results of model (1) with homoskedastic disturbances

|  |  | $\lambda$ | $\rho$ | $\gamma$ | $\beta$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $n=196$ |  |  |  |  |  |
| Normally distributed $\tau_{n i}$ 's, $\kappa=0$ | BGMM | -0.002[0.044] 0.044 | -0.001[0.127]0.127 | $0.003[0.072] 0.072$ | -0.003[0.072]0.072 |
|  | GMM2 | 0.003[0.045]0.045 | $0.001[0.131] 0.131$ | $0.014[0.070] 0.072$ | -0.003[0.071]0.071 |
|  | GMM3 | -0.003[0.044] 0.044 | -0.008[0.127]0.127 | -0.001[0.072]0.072 | -0.003[0.072]0.072 |
|  | GS2SLS | 0.003[0.076]0.076 | -0.002[0.141]0.141 | 0.002[0.073]0.073 | -0.004[0.072]0.072 |
| Normally distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | -0.000[0.039]0.039 | $-0.004[0.133] 0.133$ | $0.000[0.071] 0.071$ | -0.002[0.072]0.072 |
|  | GMM2 | 0.000[0.040]0.040 | -0.002[0.133]0.134 | $0.010[0.071] 0.071$ | -0.003[0.072]0.072 |
|  | GMM3 | -0.001[0.040]0.040 | -0.010[0.130]0.130 | -0.003[0.073]0.073 | -0.003[0.072]0.072 |
|  | GS2SLS | 0.001[0.065]0.065 | -0.002[0.145]0.145 | -0.001[0.075]0.075 | -0.002[0.073]0.073 |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0$ | BGMM | $-0.000[0.042] 0.042$ | $0.004[0.131] 0.132$ | $-0.000[0.061] 0.061$ | $-0.003[0.061] 0.061$ |
|  | GMM2 | $0.004[0.045] 0.045$ | -0.002[0.130]0.130 | 0.013 [0.072]0.073 | -0.004[0.073]0.073 |
|  | GMM3 | -0.000[0.042]0.042 | $0.004[0.130] 0.130$ | -0.000[0.062]0.062 | $-0.003[0.061] 0.061$ |
|  | GS2SLS | 0.005[0.077]0.077 | -0.003[0.145]0.145 | $0.001[0.074] 0.074$ | $-0.004[0.074] 0.074$ |
| Gamma-distributed $\tau_{n i}$ 's, $\kappa=0.5$ | BGMM | -0.002[0.038]0.038 | $0.000[0.133] 0.133$ | $0.000[0.060] 0.060$ | $-0.002[0.061] 0.061$ |
|  | GMM2 | -0.000[0.040]0.040 | $-0.004[0.132] 0.132$ | $0.013[0.070] 0.072$ | -0.002[0.073]0.073 |
|  | GMM3 | -0.001[0.039]0.039 | $0.000[0.132] 0.132$ | $0.000[0.062] 0.062$ | -0.002[0.062]0.062 |
|  | GS2SLS | -0.000[0.065]0.065 | -0.004[0.143]0.143 | $0.002[0.075] 0.075$ | -0.002[0.073]0.073 |
| $n=392$ |  |  |  |  |  |
| Normally distributed $\tau_{n i}$ 's, $\kappa=0$ | BGMM | $-0.000[0.030] 0.030$ | 0.001[0.091]0.091 | $0.001[0.051] 0.051$ | $-0.001[0.051] 0.051$ |
|  | GMM2 | 0.002[0.031]0.031 | 0.001[0.092]0.092 | $0.007[0.050] 0.051$ | $-0.001[0.051] 0.051$ |
|  | GMM3 | -0.001[0.030]0.030 | -0.003[0.091]0.091 | $-0.001[0.051] 0.051$ | -0.001[0.051]0.051 |
|  | GS2SLS | 0.001[0.054] 0.054 | $0.000[0.100] 0.100$ | $0.001[0.051] 0.051$ | -0.001[0.052]0.052 |
| Normally distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | $-0.000[0.027] 0.027$ | -0.003[0.092]0.092 | $0.001[0.051] 0.051$ | -0.002[0.050]0.051 |
|  | GMM2 | -0.000[0.027]0.027 | -0.001[0.092]0.092 | $0.006[0.051] 0.051$ | -0.002[0.051]0.051 |
|  | GMM3 | -0.001[0.027]0.027 | -0.005[0.090]0.091 | -0.001[0.052]0.052 | -0.002[0.050]0.051 |
|  | GS2SLS | -0.002[0.044]0.044 | 0.000[0.098]0.098 | $0.001[0.053] 0.053$ | $-0.002[0.051] 0.051$ |
| Gamma-distributed $\tau_{n i}$ 's, $\kappa=0$ | BGMM | $-0.000[0.028] 0.028$ | $0.004[0.092] 0.092$ | $0.001[0.042] 0.042$ | $-0.001[0.042] 0.042$ |
|  | GMM2 | 0.002[0.031]0.031 | 0.001[0.092]0.092 | $0.008[0.051] 0.052$ | $-0.001[0.050] 0.050$ |
|  | GMM3 | -0.000[0.029]0.029 | $0.004[0.091] 0.091$ | $0.001[0.042] 0.042$ | -0.001[0.042]0.042 |
|  | GS2SLS | -0.000[0.054]0.054 | 0.001[0.099]0.099 | $0.002[0.052] 0.052$ | $-0.001[0.051] 0.051$ |
| Gamma-distributed $\tau_{n i}$ 's, $\kappa=0.5$ | BGMM | $-0.001[0.025] 0.025$ | 0.002[0.091]0.091 | $0.000[0.042] 0.042$ | -0.001[0.042]0.042 |
|  | GMM2 | -0.001[0.027]0.027 | -0.001[0.091]0.091 | $0.007[0.050] 0.051$ | -0.001[0.051]0.051 |
|  | GMM3 | -0.000[0.025]0.025 | 0.002[0.090]0.090 | $0.000[0.042] 0.042$ | -0.001[0.042]0.042 |
|  | GS2SLS | -0.001[0.044]0.044 | -0.000[0.097]0.097 | 0.002[0.053]0.053 | -0.001[0.052]0.052 |

The three numbers in each cell are bias[SD]RMSE. $\left[\lambda_{0}, \rho_{0}, \gamma_{0}, \beta_{0}\right]=[0.5,0.2,1,1]$.

Table 4: Estimation results of model (1) with heteroskedastic disturbances

|  |  | $\lambda$ | $\rho$ | $\gamma$ | $\beta$ |
| :--- | :--- | :---: | :---: | :---: | :---: |
| $n=196$ |  |  |  |  |  |
| Normally distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0$ | BGMM | $-0.001[0.042] 0.042$ | $-0.002[0.128] 0.128$ | $0.005[0.074] 0.074$ | $-0.003[0.073] 0.073$ |
|  | GMM2 | $0.003[0.043] 0.043$ | $0.000[0.131] 0.131$ | $0.017[0.073] 0.075$ | $-0.003[0.073] 0.073$ |
|  | GMM3 | $-0.002[0.043] 0.043$ | $-0.009[0.127] 0.128$ | $0.001[0.074] 0.074$ | $-0.003[0.073] 0.073$ |
|  | GS2SLS | $0.002[0.073] 0.073$ | $-0.003[0.143] 0.143$ | $0.005[0.074] 0.074$ | $-0.003[0.074] 0.074$ |
| Normally distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | $-0.001[0.038] 0.038$ | $-0.003[0.134] 0.134$ | $0.003[0.071] 0.071$ | $-0.001[0.072] 0.072$ |
|  | GMM2 | $-0.001[0.039] 0.039$ | $0.000[0.133] 0.133$ | $0.013[0.071] 0.072$ | $-0.001[0.073] 0.073$ |
|  | GMM3 | $-0.002[0.038] 0.038$ | $-0.009[0.130] 0.130$ | $-0.001[0.073] 0.073$ | $-0.001[0.072] 0.072$ |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0$ | BGMM | $-0.000[0.043] 0.043$ | $0.011[0.130] 0.131$ | $0.006[0.072] 0.072$ | $-0.004[0.072] 0.072$ |
|  | GMM2 | $0.003[0.043] 0.043$ | $0.003[0.132] 0.132$ | $0.015[0.071] 0.072$ | $-0.005[0.072] 0.072$ |
|  | GMM3 | $-0.001[0.044] 0.044$ | $0.005[0.130] 0.130$ | $0.001[0.072] 0.072$ | $-0.004[0.072] 0.072$ |
| Gamma-distributed $\tau_{n i}{ }^{\prime}$ 's, $\kappa=0.5$ | BGMM | $-0.000[0.038] 0.038$ | $0.008[0.132] 0.132$ | $0.002[0.070] 0.070$ | $-0.003[0.073] 0.073$ |
|  | GMM2 | $-0.001[0.038] 0.038$ | $-0.001[0.131] 0.131$ | $0.011[0.070] 0.070$ | $-0.002[0.072] 0.072$ |
|  | GMSS | $0.005[0.071] 0.071$ | $-0.003[0.143] 0.143$ | $0.003[0.073] 0.073$ | $-0.004[0.073] 0.073$ |
|  | GMM3 | $-0.001[0.038] 0.038$ | $0.003[0.128] 0.128$ | $-0.001[0.072] 0.072$ | $-0.003[0.073] 0.073$ |
|  | GS2SLS | $0.001[0.060] 0.060$ | $-0.004[0.141] 0.141$ | $-0.001[0.074] 0.074$ | $-0.003[0.073] 0.073$ |
|  |  |  |  |  |  |

The three numbers in each cell are bias[SD]RMSE. $\left[\lambda_{0}, \rho_{0}, \gamma_{0}, \beta_{0}\right]=[0.5,0.2,1,1]$.

For a square matrix $A, \operatorname{diag}(A)$ is a diagonal matrix formed by the diagonal elements of $A$; for a vector $a, \operatorname{diag}(a)$ is a diagonal matrix formed by the elements of $a . \quad \sigma_{n i}^{2}=\mathrm{E}\left(\epsilon_{n i}^{2}\right)$ and $\Sigma_{n}=\operatorname{diag}\left(\sigma_{n 1}^{2}, \cdots, \sigma_{n n}^{2}\right)$.

For any square matrix $A, A^{s}=A+A^{\prime}, d_{A}$ is a column vector formed by the diagonal elements of $A$, and $\operatorname{vec}(A)$ is the vectorization of $A$.
$\omega_{n}=\left[\operatorname{vec}\left(P_{1 n}^{s}\right), \cdots, \operatorname{vec}\left(P_{k_{p} n}^{s}\right)\right], \omega_{n d}=\left[d_{P_{1 n}}, \cdots, d_{P_{k_{p} n}}\right], \Sigma_{n}^{1 / 2}=\operatorname{diag}\left(\sigma_{n 1}, \cdots, \sigma_{n n}\right)$, and $\omega_{n h}=$ $\left[\operatorname{vec}\left(\Sigma_{n}^{1 / 2} P_{1 n}^{s} \Sigma_{n}^{1 / 2}\right), \cdots, \operatorname{vec}\left(\Sigma_{n}^{1 / 2} P_{k_{p} n}^{s} \Sigma_{n}^{1 / 2}\right)\right]$.

In the case that $\epsilon_{n i}$ 's are i.i.d., $\sigma_{0}^{2}=\mathrm{E}\left(\epsilon_{n i}^{2}\right), \mu_{30}=\mathrm{E}\left(\epsilon_{n i}^{3}\right), \mu_{40}=\mathrm{E}\left(\epsilon_{n i}^{4}\right), \xi=\frac{\sqrt{2}}{2}\left(\frac{\mu_{40}}{\sigma_{0}^{4}}-1-\frac{\mu_{30}^{2}}{\sigma_{0}^{6}}\right)^{1 / 2}$, $P_{j n, \xi}^{s}=\xi \operatorname{diag}\left(P_{j n}^{s}\right)+\left[P_{j n}^{s}-\operatorname{diag}\left(P_{j n}^{s}\right)\right], \omega_{n \xi}=\left[\operatorname{vec}\left(P_{1 n, \xi}^{s}\right), \cdots, \operatorname{vec}\left(P_{k_{p} n, \xi}^{s}\right)\right]$.
$\zeta_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right), \Psi_{n}=R_{n} T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), l_{n}$ is an $n \times 1$ vector of ones, and $\tilde{a}_{n}=$ $a_{n}-\frac{1}{n} l_{n} l_{n}^{\prime} a_{n}$ for any $n \times 1$ vector $a_{n}$.

## Appendix B Best linear and quadratic moments for a special model with no SAR disturbances

In this section, we consider the best linear and quadratic moments for the following model:

$$
\begin{equation*}
Y_{n}=\lambda W_{n} Y_{n}+Z_{n} \gamma+X_{n} \beta+\epsilon_{n} \tag{B.1}
\end{equation*}
$$

where elements of $\epsilon_{n}$ are i.i.d. with mean zero and variance $\sigma_{0}^{2}$, and the notations are the same as those in the main text. Model (B.1) is a special model nested in model (1). The GMM estimation of (B.1) still has the objective function (4), where the moment vector $g_{n}(\theta)$ has the form (3), but $\theta$ reduces to $\left[\lambda, \gamma, \beta^{\prime}\right]^{\prime}$ and $\epsilon_{n}(\theta)=S_{n}(\lambda) Y_{n}-Z_{n} \gamma-X_{n} \beta$. The best linear and quadratic moments for model (B.1) are presented in the following Corollary 1. Let $\Phi_{n}=T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right)$, $\varsigma_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+\epsilon_{n}\right), \mathbb{C}_{1 n}=\mathrm{E}\left(\varsigma_{n} \epsilon_{n}^{\prime}\right)-I_{n} \operatorname{tr}\left[\mathrm{E}\left(\varsigma_{n} \epsilon_{n}^{\prime}\right)\right] / n$, and $\mathbb{C}_{1+j, n}=\mathrm{E}\left(\check{Z}_{n, j} \epsilon_{n}^{\prime}\right)-I_{n} \operatorname{tr}\left[\mathrm{E}\left(\check{Z}_{n, j} \epsilon_{n}^{\prime}\right)\right] / n$ for $j=1, \ldots, k_{z}$.

Corollary 1. The following results hold for the GMM estimation of model (B.1) with i.i.d. disturbances.
(a) The best $Q_{n}$ and $P_{j n}$ 's that can generate an OGMM estimator with the minimum asymptotic variance are

$$
\begin{aligned}
Q_{n}^{*}= & {\left[\Phi_{n}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{\mathbb{C}_{1 n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \tilde{\Phi}_{n},\right.} \\
& \bar{Z}_{n, 1}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{\mathbb{C}_{2 n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{\bar{Z}_{n, 1}}, \cdots, \bar{Z}_{n, k_{z}}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{\mathbb{C}_{k_{z}+1, n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{\bar{Z}_{n, k_{z}}} \\
& \left.X_{n, 1}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{X_{n, 1}, \cdots}, \cdots, X_{n, k_{x}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{X_{n, k_{x}}}\right]
\end{aligned}
$$

$P_{1 n}^{*}=\left[\mathbb{C}_{1 n}-\operatorname{diag}\left(\mathbb{C}_{1 n}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(\mathbb{C}_{1 n}\right)-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{\Phi}_{n}\right), P_{1+j, n}^{*}=\left[\mathbb{C}_{1+j, n}-\operatorname{diag}\left(\mathbb{C}_{1+j, n}\right)\right]+$ $\frac{1}{\xi^{2}} \operatorname{diag}\left(\mathbb{C}_{1+j, n}\right)-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\widetilde{\overline{Z_{n, j}}}\right)$ for $j=1, \ldots, k_{z}$, and $P_{1+k_{z}+j, n}^{*}=\operatorname{diag}\left(\widetilde{X_{n, j}}\right)$ for $j=$ $1, \ldots, k_{x}$.
(b) The OGMM estimator with the above $Q_{n}^{*}$ and $P_{j n}^{*}$ 's, denoted by $\hat{\theta}_{\mathrm{BGMM}}$, has the asymptotic distribution $\sqrt{n}\left(\hat{\theta}_{\mathrm{BGMM}}-\theta_{0}\right) \xrightarrow{d} N\left(0, \lim _{n \rightarrow \infty}\left(\frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}\right)^{-1}\right)$, where

$$
\Gamma_{n}=\left(\begin{array}{cc}
\Gamma_{n, 11} & -\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}}\left[\operatorname{vec}\left(\operatorname{diag}\left(\widetilde{X_{n, \cdot 1}}\right)\right), \cdots, \operatorname{vec}\left(\operatorname{diag}\left(\widetilde{X_{n, k_{x}}}\right)\right)\right] \\
\frac{1}{\sigma_{0}}\left[\Phi_{n}, 0_{n \times 1}, \bar{Z}_{n}\right] & \frac{1}{\sigma_{0}} X_{n}
\end{array}\right)
$$

with

$$
\begin{aligned}
\Gamma_{n, 11}= & \frac{1}{\sqrt{2} \sigma_{0}^{2}}\left[\operatorname{vec}\left(\mathbb{C}_{1 n, 1 / \xi}^{s}-\frac{\mu_{30}}{\xi \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{\Phi}_{n}\right)\right)\right. \\
& \left.\operatorname{vec}\left(\mathbb{C}_{2 n, 1 / \xi}^{s}-\frac{\mu_{30}}{\xi \sigma_{0}^{2}} \operatorname{diag}\left(\widetilde{\bar{Z}_{n, 1}}\right)\right), \cdots, \operatorname{vec}\left(\mathbb{C}_{k_{z}+1, n, 1 / \xi}^{s}-\frac{\mu_{30}}{\xi \sigma_{0}^{2}} \operatorname{diag}\left(\widetilde{\bar{Z}_{n, k_{z}}}\right)\right)\right]
\end{aligned}
$$

(c) When $\mu_{30}=0$, the quadratic matrices $\operatorname{diag}\left(\widetilde{X_{n, j}}\right)$ for $j=1, \ldots, k_{x}$ are redundant, so $Q_{n}^{*}$ reduces to $Q_{n}^{*}=\left[\Phi_{n}, \bar{Z}_{n}, X_{n}\right]$ and $P_{j n}^{*}$ 's are $P_{j n}^{*}=\left[\mathbb{C}_{j n}-\operatorname{diag}\left(\mathbb{C}_{j n}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(\mathbb{C}_{j n}\right)$ for $j=$ $1, \ldots, k_{z}+1$.
(d) For $Q_{n}^{*}$ and $P_{j n}^{*}$ 's in (a), if we use the IVs in each column of $Q_{n}^{*}$ and the quadratic matrices in each $P_{j n}^{*}$ separately, then $Q_{n}^{*}=\left[\Phi_{n}, \bar{Z}_{n}, X_{n}, d_{C_{1 n}}, \cdots, d_{C_{k_{z}+1, n}}, l_{n}\right]$, and $P_{j n}^{*}$ 's are $\mathbb{C}_{j n}-$ $\operatorname{diag}\left(\mathbb{C}_{j n}\right)$ for $j=1, \ldots, k_{z}+1, \operatorname{diag}\left(\mathbb{C}_{j n}\right)$ for $j=1, \ldots, k_{z}+1, \operatorname{diag}\left(\tilde{\Phi}_{n}\right), \operatorname{diag}\left(\widetilde{\bar{Z}_{n, j}}\right)$ for $j=1, \ldots, k_{z}$, and $\operatorname{diag}\left(\widetilde{X_{n, j}}\right)$ for $j=1, \ldots, k_{x}$.
When $\mu_{30}=0, Q_{n}^{*}=\left[\Phi_{n}, \bar{Z}_{n}, X_{n}\right]$, and $P_{j n}^{*}$ 's are $P_{j n}^{*}=\mathbb{C}_{j n}-\operatorname{diag}\left(\mathbb{C}_{j n}\right)$ for $j=1, \ldots, k_{z}+1$, and $P_{1+k_{z}+j, n}^{*}=\operatorname{diag}\left(\mathbb{C}_{j n}\right)$ for $j=1, \ldots, k_{z}+1$.
If we have an IV matrix $F_{n}$ for $Z_{n}$, the 2SLS estimate of $Z_{n}$ is $\hat{Z}_{n}=F_{n}\left(F_{n}^{\prime} F_{n}\right)^{-1} F_{n}^{\prime} Z_{n}$, which is an estimate of $\bar{Z}_{n}$. By Corollary $1(a)$, as $\varsigma_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+\epsilon_{n}\right)$ and $\Phi_{n}=T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), P_{j n}$ 's can be taken as

$$
\begin{array}{r}
\sigma_{0}^{2}\left[T_{n}-\operatorname{diag}\left(T_{n}\right)\right]+\frac{\sigma_{0}^{2}}{\xi^{2}} \operatorname{diag}\left(T_{n}-\frac{\operatorname{tr}\left(T_{n}\right)}{n} I_{n}\right)-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{\boldsymbol{\Pi}}_{n}\right)  \tag{B.2}\\
\operatorname{diag}\left(\widetilde{\hat{Z}_{n, 1}}\right), \cdots, \operatorname{diag}\left(\widetilde{\hat{Z}_{n, \cdot k_{z}}}\right), \operatorname{diag}\left(\widetilde{X_{n, 1}}\right), \cdots, \operatorname{diag}\left(\widetilde{X_{n, k_{x}}}\right)
\end{array}
$$

where $\boldsymbol{\Pi}_{n}=T_{n}\left(\hat{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right)$, and the IV matrix $Q_{n}$ can be taken as

$$
\begin{align*}
& {\left[\boldsymbol{\Pi}_{n}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{2}} d_{T_{n}-I_{n} \operatorname{tr}\left(T_{n}\right) / n}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \tilde{\boldsymbol{\Pi}}_{n}, \hat{Z}_{n, \cdot 1}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{\hat{Z}_{n, 1}}, \cdots, \hat{Z}_{n, k_{z}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{\hat{Z}_{n, k_{z}}}\right.} \\
& \left.\quad X_{n, 1}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{X_{n, \cdot 1}}, \cdots, X_{n, k_{x}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \widetilde{X_{n, k_{x}}}\right] \tag{B.3}
\end{align*}
$$

When $\mu_{30}=0$, the quadratic matrices $\operatorname{diag}\left(\widetilde{\hat{Z}_{n, 1}}\right), \ldots, \operatorname{diag}\left(\widetilde{\hat{Z}_{n, k_{z}}}\right), \operatorname{diag}\left(\widetilde{X_{n,-1}}\right), \ldots, \operatorname{diag}\left(\widetilde{X_{n, k_{x}}}\right)$ in (B.2) are redundant.

## Appendix C Proofs

Proof of Lemma 1. The discussion in the main text shows that, if $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+\right.\right.$ $\left.\left.X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has full column rank for any $\rho$ in its parameter space $\boldsymbol{\rho}$, the linear moment part of $\lim _{n \rightarrow \infty} \mathrm{E}\left[g_{n}(\theta)\right]=0$ implies that $(\lambda, \gamma, \beta)=\left(\lambda_{0}, \gamma_{0}, \beta_{0}\right)$. With $(\lambda, \gamma, \beta)=\left(\lambda_{0}, \gamma_{0}, \beta_{0}\right)$, by (6), $\mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]$ reduces to $\mathrm{E}\left[\epsilon_{n}^{\prime} R_{n}^{\prime-1} R_{n}^{\prime}(\rho) P_{j n} R_{n}(\rho) R_{n}^{-1} \epsilon_{n}\right]$. Then a sufficient identification condition for $\rho_{0}$ is that ${ }^{9}$

$$
\begin{align*}
& \lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left[\epsilon_{n}^{\prime} R_{n}^{\prime-1} R_{n}^{\prime}(\rho) P_{j n} R_{n}(\rho) R_{n}^{-1} \epsilon_{n}\right]=0 \text { for } j=1, \ldots, k_{p} \text { have a unique solution at }  \tag{C.1}\\
& \quad \rho=\rho_{0} \text { for } \rho \in \rho .
\end{align*}
$$

This identification condition corresponds to that of a pure SAR process $u_{n}=\rho M_{n} u_{n}+\epsilon_{n}$ as if $u_{n}$ were observable, which is the same as that in Liu et al. (2010). Let $H_{n}=M_{n} R_{n}^{-1}$, and $\Xi=\left[\Xi_{j k}\right]$ be a $k_{p} \times 2$ matrix with $\Xi_{j 1}=\lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n}^{s} H_{n} \epsilon_{n}\right)$ and $\Xi_{j 2}=\lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} H_{n}^{\prime} P_{j n}^{s} H_{n} \epsilon_{n}\right)$ for $j=1, \ldots, k_{p}$, where $A^{s}=A+A^{\prime}$ for any square matrix $A$. Since $\mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n} \epsilon_{n}\right)=0$ and $R_{n}(\rho)=R_{n}+\left(\rho_{0}-\rho\right) M_{n}$ is linear in $\rho, \lim _{n \rightarrow \infty} \mathrm{E}\left[\epsilon_{n}^{\prime} R_{n}^{\prime-1} R_{n}^{\prime}(\rho) P_{j n} R_{n}(\rho) R_{n}^{-1} \epsilon_{n}\right]=0$ for $j=1, \ldots, k_{p}$ can be written as $\left(\rho_{0}-\rho\right) \Xi\binom{1}{\left(\rho_{0}-\rho\right) / 2}=0$. Let $\Xi_{1}$ and $\Xi_{2}$ be, respectively, the first column and the second column of $\Xi$. Then (C.1) is equivalent to the condition that

$$
\begin{equation*}
\Xi_{1}+\frac{\rho_{0}-\rho}{2} \Xi_{2} \neq 0 \text { when } \rho \in \boldsymbol{\rho} \text { and } \rho \neq \rho_{0} \tag{C.2}
\end{equation*}
$$

If $\Xi$ has full column rank, then (C.2) holds. Even if $\Xi$ has reduced column rank, the linear combination $\Xi_{1}+\frac{\rho_{0}-\rho}{2} \Xi_{2}$ may still be nonzero for any $\rho \in \boldsymbol{\rho}$ and $\rho \neq \rho_{0}$, since the combination $\Xi_{1}+\frac{\rho_{0}-\rho}{2} \Xi_{2}$ may be only zero for some $\rho \notin \rho .{ }^{10}$ We may derive some sufficient conditions for (C.2) to hold in the case that $\Xi$ has reduced column rank. If $\Xi_{1}=0$, then $\Xi_{2} \neq 0$ is sufficient; if $\Xi_{2}=0$, then $\Xi_{1} \neq 0$ is sufficient. Thus, the following condition is sufficient for (C.2):

> Either $(i) \Xi$ has full column rank; or $(i i) \Xi_{1}=0$, and $\Xi_{k 2} \neq 0$ for some $k$; or $(i i i) \Xi_{j 1} \neq 0$ for some $j$, and $\Xi_{2}=0$.

If $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has reduced column rank for some $\rho \in \boldsymbol{\rho}$, as $Q_{n}$ usually includes $X_{n}$, we maintain in Assumption 6(ii) that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho) X_{n}$ has full column rank for any $\rho \in \boldsymbol{\rho}$. Assume that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has column rank $\left(k_{x}+k_{0}\right)$ for some $0 \leq k_{0}<k_{z}+1$. Let $\bar{Z}_{n}=\left[\bar{Z}_{1 n}, \bar{Z}_{2 n}\right]$, where $\bar{Z}_{1 n}$ is $n \times\left(k_{z}-k_{0}\right)$ and $\bar{Z}_{2 n}$ is $n \times k_{0}$. Without loss of generality, assume that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[\bar{Z}_{2 n}, X_{n}\right]$ has full column rank for any

[^8]$\rho \in \boldsymbol{\rho} .^{11}$ Then, for a large enough $n$, there is some $\left(k_{x}+k_{0}\right) \times 1$ vector $c_{1}$ and some $\left(k_{x}+k_{0}\right) \times\left(k_{z}-k_{0}\right)$ matrix $c_{2}$ such that $T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right)=\left[\bar{Z}_{2 n}, X_{n}\right] c_{1}$ and $\bar{Z}_{1 n}=\left[\bar{Z}_{2 n}, X_{n}\right] c_{2}$. Denote $\gamma=\left[\gamma_{1}^{\prime}, \gamma_{2}^{\prime}\right]^{\prime}$, where $\gamma_{1}$ is $\left(k_{z}-k_{0}\right) \times 1$ and $\gamma_{2}$ is $k_{0} \times 1$. Correspondingly, denote $\gamma_{0}=\left[\gamma_{10}^{\prime}, \gamma_{20}^{\prime}\right]^{\prime}$. Thus,
$$
\mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=Q_{n}^{\prime} R_{n}(\rho)\left[\bar{Z}_{2 n}, X_{n}\right]\left[\left(\lambda_{0}-\lambda\right) c_{1}+c_{2}\left(\gamma_{10}-\gamma_{1}\right)+\binom{\gamma_{20}-\gamma_{2}}{\beta_{0}-\beta}\right] .
$$

Hence, $\lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=0$ implies that $\left(\lambda_{0}-\lambda\right) c_{1}+c_{2}\left(\gamma_{10}-\gamma_{1}\right)+\binom{\gamma_{20}-\gamma_{2}}{\beta_{0}-\beta}=0$, and thus $\bar{\epsilon}_{n}(\theta)=0$. Then, as long as $\lambda_{0}$ and $\gamma_{10}$ are identified, $\gamma_{20}$ and $\beta_{0}$ are identified. The identification of $\lambda_{0}$ and $\gamma_{10}$ can be from the quadratic moments. As $\bar{\epsilon}_{n}(\theta)=0$ for a large enough $n, \mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]=\mathrm{E}\left[\check{\epsilon}_{n}^{\prime}(\theta) P_{j n} \check{\epsilon}_{n}(\theta)\right]$. Therefore, we have the following sufficient identification condition:

$$
\begin{align*}
& \lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \check{\epsilon}_{n}(\theta)\right]=0 \text { for } j=1, \ldots, k_{p}, \text { have a unique solution at }  \tag{C.4}\\
& \quad(\lambda, \rho, \gamma)=\left(\lambda_{0}, \rho_{0}, \gamma_{0}\right) \text { for } \theta \in \Theta
\end{align*}
$$

Since $\check{\epsilon}_{n}(\theta)$ is linear in each element of $\theta$, we can expand each $\mathrm{E}\left[\check{\epsilon}_{n}^{\prime}(\theta) P_{j n} \check{\epsilon}_{n}(\theta)\right]$ as a polynomial function of $\theta-\theta_{0}$. Correspondingly, (C.4) can be written in an equivalent way where each element is a polynomial of $\theta-\theta_{0}$.

Proof of Proposition 1. We first prove that $g_{n}(\theta)-\mathrm{E}\left[g_{n}(\theta)\right]=o_{p}(1)$. With $\check{\epsilon}_{n}(\theta)$ in (8), $\frac{1}{n} Q_{n}^{\prime} \epsilon_{n}(\theta)-$ $\frac{1}{n} \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=\frac{1}{n} Q_{n}^{\prime} \check{\epsilon}_{n}(\theta)=\frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[R_{n}^{-1} \epsilon_{n}+\left(\lambda_{0}-\lambda\right) T_{n} R_{n}^{-1} \epsilon_{n}\right]+\frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[\left(\lambda_{0}-\lambda\right) T_{n} \check{Z}_{n} \gamma_{0}+\right.$ $\check{Z}_{n}\left(\gamma_{0}-\gamma\right)$ ]. For simplicity, we abbreviate "bounded in both row and column sum matrix norms" as UB. By Lemma A. 4 in Lin and Lee (2010), under Assumptions 1 and $4, \frac{1}{n} Q_{n}^{\prime} K_{n} \epsilon_{n}=o_{p}(1)$, where $K_{n}$ is an $n \times n$ UB matrix. Thus, with $R_{n}(\rho)=I_{n}-\rho M_{n}$, we have $\frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[R_{n}^{-1} \epsilon_{n}+\right.$ $\left.\left(\lambda_{0}-\lambda\right) T_{n} R_{n}^{-1} \epsilon_{n}\right]=o_{p}(1)$ under Assumptions 1, 2 and 4. By Assumption 8, $\frac{1}{n} Q_{n}^{\prime} A_{n} \check{Z}_{n}=o_{p}(1)$ for $A_{n}=I_{n}, M_{n}, T_{n}$ and $M_{n} T_{n}$. Thus, $\frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[\left(\lambda_{0}-\lambda\right) T_{n} \check{Z}_{n} \gamma_{0}+\check{Z}_{n}\left(\gamma_{0}-\gamma\right)\right]=o_{p}(1)$. Hence, $\frac{1}{n} Q_{n}^{\prime} \epsilon_{n}(\theta)-\frac{1}{n} \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=o_{p}(1)$, where $\frac{1}{n} \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=\frac{1}{n} Q_{n}^{\prime} \bar{\epsilon}_{n}(\theta)=O(1)$ under Assumptions 2-4. With $\bar{\epsilon}_{n}(\theta)$ in (7) and $\check{\epsilon}_{n}(\theta)$ in (8),

$$
\begin{align*}
\frac{1}{n} \mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]= & \frac{1}{n} \bar{\epsilon}_{n}^{\prime}(\theta) P_{j n} \bar{\epsilon}_{n}(\theta)+\frac{1}{2 n} \mathrm{E}\left[\check{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)\right]  \tag{C.5}\\
\frac{1}{n} \epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)-\frac{1}{n} \mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]= & \frac{1}{n} \bar{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)  \tag{C.6}\\
& +\frac{1}{2 n}\left\{\check{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)-\mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)\right]\right\}
\end{align*}
$$

where $\frac{1}{n} \bar{\epsilon}_{n}^{\prime}(\theta) P_{j n} \bar{\epsilon}_{n}(\theta)=O(1)$, and

$$
\frac{1}{n} \bar{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)=\frac{1}{n}\left[\left(\lambda_{0}-\lambda\right) \gamma_{0}^{\prime},\left(\lambda_{0}-\lambda\right) \beta_{0}^{\prime},\left(\gamma_{0}-\gamma\right)^{\prime},\left(\beta_{0}-\beta\right)^{\prime}\right] \Upsilon_{1 n}^{\prime} P_{j n}^{s} \check{\epsilon}_{n}(\theta)
$$

[^9]$$
-\frac{1}{n} \rho\left[\left(\lambda_{0}-\lambda\right) \gamma_{0}^{\prime},\left(\lambda_{0}-\lambda\right) \beta_{0}^{\prime},\left(\gamma_{0}-\gamma\right)^{\prime},\left(\beta_{0}-\beta\right)^{\prime}\right] \Upsilon_{1 n}^{\prime} M_{n}^{\prime} P_{j n}^{s} \check{\epsilon}_{n}(\theta)
$$
with $\Upsilon_{1 n}=\left[T_{n} \bar{Z}_{n}, T_{n} X_{n}, \bar{Z}_{n}, X_{n}\right]$. By an argument similar to that for $\frac{1}{n} Q_{n}^{\prime} \epsilon_{n}(\theta)-\frac{1}{n} \mathrm{E}\left[Q_{n}^{\prime} \epsilon_{n}(\theta)\right]=$ $o_{p}(1), \frac{1}{n} \bar{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)=o_{p}(1)$. By (8),
\[

$$
\begin{align*}
\check{\epsilon}_{n}(\theta)= & {\left[R_{n}+\left(\rho_{0}-\rho\right) M_{n}\right]\left[R_{n}^{-1} \epsilon_{n}+\left(\lambda_{0}-\lambda\right) \zeta_{n}+\check{Z}_{n}\left(\gamma_{0}-\gamma\right)\right] } \\
= & \epsilon_{n}+\left(\rho_{0}-\rho\right) H_{n} \epsilon_{n}+\left(\lambda_{0}-\lambda\right) R_{n} \zeta_{n}+\left(\rho_{0}-\rho\right)\left(\lambda_{0}-\lambda\right) M_{n} \zeta_{n}  \tag{C.7}\\
& +R_{n} \check{Z}_{n}\left(\gamma_{0}-\gamma\right)+M_{n} \check{Z}_{n}\left(\gamma_{0}-\gamma\right)\left(\rho_{0}-\rho\right) .
\end{align*}
$$
\]

where $\zeta_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right)$ and $H_{n}=M_{n} R_{n}^{-1}$. Then we may expand $\frac{1}{n} \check{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)$ as a multivariate polynomial of $\theta$. Under Assumption 1, for an $n \times n$ UB matrix $K_{n}, \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} K_{n} \epsilon_{n}\right)=O(1)$ and $\frac{1}{n} \epsilon_{n}^{\prime} K_{n} \epsilon_{n}-\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} K_{n} \epsilon_{n}\right)=o_{p}(1)$ by Lemma A. 3 in Lin and Lee (2010). Let $A_{n}$ and $B_{n}$ be either $I_{n}, M_{n}, T_{n}$ or $M_{n} T_{n}$; and $C_{n}$ be either $I_{n}, H_{n}, T_{n} R_{n}^{-1}$ or $M_{n} T_{n} R_{n}^{-1}$. Under Assumption 8 , terms with the forms $\frac{1}{n} \check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}$ and $\frac{1}{n} \epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}$ in the expression of $\frac{1}{n} \check{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)$ satisfy $\frac{1}{n} \mathrm{E}\left(\check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=O(1), \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=O(1), \frac{1}{n} \check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}-\frac{1}{n} \mathrm{E}\left(\check{Z}_{n}^{\prime} B_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=$ $o_{p}(1)$ and $\frac{1}{n} \epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}-\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} C_{n}^{\prime} P_{j n}^{s} A_{n} \check{Z}_{n}\right)=o_{p}(1)$. Hence, as $\zeta_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right)$, by (C.7), $\frac{1}{n} \mathrm{E}\left[\check{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)\right]=O(1)$ and $\frac{1}{n} \breve{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)-\frac{1}{n} \mathrm{E}\left[\check{\epsilon}_{n}^{\prime}(\theta) P_{j n}^{s} \check{\epsilon}_{n}(\theta)\right]=o_{p}(1)$. Therefore, by (C.5)-(C.6), $\frac{1}{n} \mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]=O(1)$ and $\frac{1}{n} \epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)-\frac{1}{n} \mathrm{E}\left[\epsilon_{n}^{\prime}(\theta) P_{j n} \epsilon_{n}(\theta)\right]=o_{p}(1)$. It follows that $\mathrm{E}\left[g_{n}(\theta)\right]=O(1)$ and $g_{n}(\theta)-\mathrm{E}\left[g_{n}(\theta)\right]=o_{p}(1)$. Note that $\epsilon_{n}(\theta)$ is linear in each element of $\theta$ and $g_{n}(\theta)$ is quadratic in $\epsilon_{n}(\theta)$. Then, as the parameter space $\Theta$ of $\theta$ is compact, we have the uniform convergence $\sup _{\theta \in \Theta}\left\|g_{n}(\theta)-\mathrm{E}\left[g_{n}(\theta)\right]\right\|=o_{p}(1)$. It follows that $\sup _{\theta \in \Theta} \| g_{n}^{\prime}(\theta) a_{n}^{\prime} a_{n} g_{n}(\theta)-$ $\mathrm{E}\left[g_{n}^{\prime}(\theta)\right] a_{n}^{\prime} a_{n} \mathrm{E}\left[g_{n}(\theta)\right] \|=o_{p}(1)$.

The identification condition for $\lim _{n \rightarrow \infty} a_{n} \mathrm{E}\left[g_{n}(\theta)\right]$ to be uniquely zero at $\theta=\theta_{0}$ is maintained in Assumption 7. As each element of $g_{n}(\theta)$ is a polynomial function of $\theta$, under Assumption $8, \mathrm{E}\left[g_{n}(\theta)\right]$ is uniformly equicontinuous. So is $\mathrm{E}\left[g_{n}^{\prime}(\theta)\right] a_{n}^{\prime} a_{n} \mathrm{E}\left[g_{n}(\theta)\right]$. Hence, the identification uniqueness condition holds. With a compact parameter space $\Theta$, the consistency of $\hat{\theta}$ follows from the uniform convergence that $\sup _{\theta \in \Theta}\left\|g_{n}^{\prime}(\theta) a_{n}^{\prime} a_{n} g_{n}(\theta)-\mathrm{E}\left[g_{n}^{\prime}(\theta)\right] a_{n}^{\prime} a_{n} \mathrm{E}\left[g_{n}(\theta)\right]\right\|=o_{p}(1)$ and the identification uniqueness condition (White, 1994).

Proof of Proposition 2. The first order condition of $\hat{\theta}_{\mathrm{GMM}}$ is $D_{n}^{\prime}\left(\hat{\theta}_{\mathrm{GMM}}\right) a_{n}^{\prime} a_{n} g_{n}\left(\hat{\theta}_{\mathrm{GMM}}\right)=0$, where $D_{n}(\theta)=\frac{\partial g_{n}(\theta)}{\partial \theta^{\prime}}$. By the mean value theorem, $0=D_{n}^{\prime}\left(\hat{\theta}_{\mathrm{GMM}}\right) a_{n}^{\prime} a_{n}\left[g_{n}\left(\theta_{0}\right)+D_{n}(\bar{\theta})\left(\hat{\theta}_{\mathrm{GMM}}-\theta_{0}\right)\right]$, where $\bar{\theta}$ lies between $\hat{\theta}_{\mathrm{GMM}}$ and $\theta_{0}$. Thus,

$$
\begin{equation*}
\sqrt{n}\left(\hat{\theta}_{\mathrm{GMM}}-\theta_{0}\right)=-\left[D_{n}^{\prime}\left(\hat{\theta}_{\mathrm{GMM}}\right) a_{n}^{\prime} a_{n} D_{n}(\bar{\theta})\right]^{-1} D_{n}^{\prime}\left(\hat{\theta}_{\mathrm{GMM}}\right) a_{n}^{\prime} a_{n} \sqrt{n} g_{n}\left(\theta_{0}\right) . \tag{C.8}
\end{equation*}
$$

As each element of $g_{n}(\theta)$ is a polynomial function of $\theta$, so is each element of $D_{n}(\theta)$. In addition, every coefficient for the polynomial functions of $D_{n}(\theta)$ is $O_{p}(1)$, and is $o_{p}(1)$ if its mean is deducted from it, by the proof of Proposition 1. Since $\hat{\theta}_{\text {GMM }}=\theta_{0}+o_{p}(1)$ by Proposition 1, $D_{n}(\bar{\theta})=$
$D_{n}\left(\theta_{0}\right)+o_{p}(1)=G_{n}+o_{p}(1)$, where $G_{n}=\mathrm{E}\left[D_{n}\left(\theta_{0}\right)\right]$. Since $\frac{\partial \epsilon_{n}(\theta)}{\partial \theta^{\prime}}=-\left[R_{n}(\rho) W_{n} Y_{n}, M_{n}\left(S_{n}(\lambda) Y_{n}-\right.\right.$ $\left.\left.Z_{n} \gamma-X_{n} \beta\right), R_{n}(\rho) Z_{n}, R_{n}(\rho) X_{n}\right]$ and $Y_{n}=S_{n}^{-1}\left(Z_{n} \gamma_{0}+X_{n} \beta_{0}+R_{n}^{-1} \epsilon_{n}\right)$, we have

$$
\begin{equation*}
\mathrm{E}\left(\frac{\partial \epsilon_{n}^{\prime}\left(\theta_{0}\right) P_{j n} \epsilon_{n}\left(\theta_{0}\right)}{\partial \theta^{\prime}}\right)=-\mathrm{E}\left[\epsilon_{n}^{\prime} P_{j n}^{s} R_{n} \zeta_{n}, \epsilon_{n}^{\prime} P_{j n}^{s} H_{n} \epsilon_{n}, \epsilon_{n}^{\prime} P_{j n}^{s} R_{n} \check{Z}_{n}, 0_{1 \times k_{x}}\right] \tag{C.9}
\end{equation*}
$$

where $\zeta_{n}=T_{n}\left(\check{Z}_{n} \gamma_{0}+R_{n}^{-1} \epsilon_{n}\right)$, and $\mathrm{E}\left(Q_{n}^{\prime} \frac{\partial \epsilon_{n}\left(\theta_{0}\right)}{\partial \theta^{\prime}}\right)=-Q_{n}^{\prime}\left[R_{n} T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), 0_{n \times 1}, R_{n} \bar{Z}_{n}, R_{n} X_{n}\right]$. Thus, $G_{n}$ has the expression in (11). We next prove that $\lim _{n \rightarrow \infty} G_{n}$ has full column rank under Assumption 10. Let $\alpha_{1}$ and $\alpha_{2}$ be scalars, $\alpha_{3}$ be a $k_{z} \times 1$ vector, and $\alpha_{4}$ be a $k_{x} \times 1$ vector. In the case of Assumption 6(i), the last $k_{q}$ elements of $\lim _{n \rightarrow \infty} G_{n}\left[\alpha_{1}, \alpha_{2}, \alpha_{3}^{\prime}, \alpha_{4}^{\prime}\right]^{\prime}=0$ are $-\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]\left[\alpha_{1}, \alpha_{3}^{\prime}, \alpha_{4}^{\prime}\right]^{\prime}=0$, which implies that $\left(\alpha_{1}, \alpha_{3}, \alpha_{4}\right)=$ $(0,0,0)$, under the assumption that $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}, X_{n}\right]$ has full column rank in Assumption $6(i)$. Then the first $k_{p}$ elements of $\lim _{n \rightarrow \infty} G_{n}\left[\alpha_{1}, \alpha_{2}, \alpha_{3}^{\prime}, \alpha_{4}^{\prime}\right]^{\prime}=0$ become

$$
-\lim _{n \rightarrow \infty} \frac{1}{n}\left[\mathrm{E}\left(\epsilon_{n}^{\prime} P_{1 n}^{s} H_{n} \epsilon_{n}\right), \ldots, \mathrm{E}\left(\epsilon_{n}^{\prime} P_{k_{p} n}^{s} H_{n} \epsilon_{n}\right)\right]^{\prime} \alpha_{2}=0
$$

which implies that $\alpha_{2}=0$ if, for some $j, \lim _{n \rightarrow \infty} \frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} P_{j n}^{s} H_{n} \epsilon_{n}\right) \neq 0$. In the case of Assumption $6(i i)$, the first $k_{p}$ elements of $\lim _{n \rightarrow \infty} G_{n}\left[\alpha_{1}, \alpha_{2}, \alpha_{3}^{\prime}, \alpha_{4}^{\prime}\right]^{\prime}=0$ are $\lim _{n \rightarrow \infty} G_{1 n}\left[\alpha_{1}, \alpha_{2}, \alpha_{3}^{\prime}\right]^{\prime}=0$, where $G_{1 n}$ is in (12). As $\lim _{n \rightarrow \infty} G_{1 n}$ has full column rank by Assumption 10, $\left(\alpha_{1}, \alpha_{2}, \alpha_{3}\right)=(0,0,0)$. Then the last $k_{q}$ elements of $\lim _{n \rightarrow \infty} G_{n}\left[\alpha_{1}, \alpha_{2}, \alpha_{3}^{\prime}, \alpha_{4}^{\prime}\right]^{\prime}=0$ become $-\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n} X_{n} \alpha_{4}=$ 0 , which implies that $\alpha_{4}=0$ as $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n} X_{n}$ has full column rank under Assumption $6(i i)$. Hence, $\lim _{n \rightarrow \infty} G_{n}$ has full column rank under Assumption 10. As $\lim _{n \rightarrow \infty} a_{n} G_{n}$ has full column rank, $\lim _{n \rightarrow \infty} G_{n}^{\prime} a_{n}^{\prime} a_{n} G_{n}$ is invertible. It follows by (C.8) that $\sqrt{n}\left(\hat{\theta}_{\mathrm{GMM}}-\theta_{0}\right)=$ $-\left(G_{n}^{\prime} a_{n}^{\prime} a_{n} G_{n}\right)^{-1} G_{n}^{\prime} a_{n}^{\prime} a_{n} \sqrt{n} g_{n}\left(\theta_{0}\right)+o_{p}(1)$. By the central limit theorem for linear and quadratic forms in Kelejian and Prucha $(2001), \sqrt{n} g_{n}\left(\theta_{0}\right) \xrightarrow{d} N\left(0, \Omega_{n}\right)$, where $\Omega_{n}=n \mathrm{E}\left[g_{n}\left(\theta_{0}\right) g_{n}^{\prime}\left(\theta_{0}\right)\right]$. Therefore, the asymptotic distribution in the proposition follows.

Proof of Proposition 3. With $\hat{\Omega}_{n}=\Omega_{n}+o_{p}(1)$, the proof is similar to that for the OGMM estimator of SAR models with no endogenous regressors in Proposition 2 of Lee (2007), thus we omit the proof.

Proof of Proposition 4. This proof follows the analytical approach in Jin et al. (2020) for the derivation of best linear and quadratic moments for spatial econometric models. The $\Omega_{n}$ in (13) can be written as

$$
\begin{equation*}
\Omega_{n}=\frac{1}{n} \Delta_{n}^{\prime} \Delta_{n}, \tag{C.10}
\end{equation*}
$$

where

$$
\Delta_{n}=\left(\begin{array}{cc}
\frac{\sigma_{0}^{2}}{\sqrt{2}} \omega_{n \xi} & 0  \tag{C.11}\\
\frac{\mu_{30}}{\sigma_{0}} \omega_{n d} & \sigma_{0} Q_{n}
\end{array}\right)
$$

From (C.9),

$$
\begin{align*}
& \mathrm{E}\left(\frac{\partial \epsilon_{n}^{\prime}\left(\theta_{0}\right) P_{j n} \epsilon_{n}\left(\theta_{0}\right)}{\partial \theta^{\prime}}\right) \\
& =-\left[\operatorname{tr}\left(P_{j n}^{s} R_{n} \mathrm{E}\left(\zeta_{n} \epsilon_{n}^{\prime}\right)\right), \sigma_{0}^{2} \operatorname{tr}\left(P_{j n}^{s} H_{n}\right), \operatorname{tr}\left(P_{j n}^{s} R_{n} \mathrm{E}\left(\check{Z}_{n, \cdot 1} \epsilon_{n}^{\prime}\right)\right), \ldots, \operatorname{tr}\left(P_{j n}^{s} R_{n} \mathrm{E}\left(\check{Z}_{n, k_{z}} \epsilon_{n}^{\prime}\right)\right), 0_{1 \times k_{x}}\right] \\
& =-\frac{1}{2}\left[\operatorname{tr}\left(P_{j n}^{s} C_{1 n}^{s}\right), \cdots, \operatorname{tr}\left(P_{j n}^{s} C_{k_{z}+2, n}^{s}\right), 0_{1 \times k_{x}}\right], \tag{C.12}
\end{align*}
$$

where $C_{1 n}=R_{n} \mathrm{E}\left(\zeta_{n} \epsilon_{n}^{\prime}\right)-I_{n} \operatorname{tr}\left[R_{n} \mathrm{E}\left(\zeta_{n} \epsilon_{n}^{\prime}\right)\right] / n, C_{2 n}=\sigma_{0}^{2}\left[H_{n}-I_{n} \operatorname{tr}\left(H_{n}\right) / n\right],{ }^{12} C_{j+2, n}=R_{n} \mathrm{E}\left(\check{Z}_{n, j} \epsilon_{n}^{\prime}\right)-$ $I_{n} \operatorname{tr}\left[R_{n} \mathrm{E}\left(\check{Z}_{n, j} \epsilon_{n}^{\prime}\right)\right] / n$ for $j=1, \ldots, k_{z}$, and the second equality in (C.12) holds because $P_{j n}^{s}$ has zero trace so that $\operatorname{tr}\left(P_{j n}^{s} C_{n}\right)=\frac{1}{2} \operatorname{tr}\left(P_{j n}^{s} C_{n}^{s}\right)=\frac{1}{2} \operatorname{tr}\left[P_{j n}^{s}\left(C_{n}^{s}-I_{n} \operatorname{tr}\left(C_{n}^{s}\right) / n\right)\right]$ for any $n \times n$ matrix $C_{n}$. For any two $n \times n$ matrices $A_{n}$ and $B_{n}$, and constants $a$ and $b$,

$$
\begin{aligned}
& \operatorname{tr}\left\{\left[a \operatorname{diag}\left(A_{n}\right)+\left(A_{n}-\operatorname{diag}\left(A_{n}\right)\right)\right]\left[b \operatorname{diag}\left(B_{n}\right)+\left(B_{n}-\operatorname{diag}\left(B_{n}\right)\right)\right]\right\} \\
& =\operatorname{tr}\left\{a b \operatorname{diag}\left(A_{n}\right) \operatorname{diag}\left(B_{n}\right)+\left(A_{n}-\operatorname{diag}\left(A_{n}\right)\right)\left(B_{n}-\operatorname{diag}\left(B_{n}\right)\right)\right\} .
\end{aligned}
$$

Thus,

$$
\begin{align*}
\operatorname{tr}\left(P_{j n}^{s} C_{k n}^{s}\right) & =\operatorname{tr}\left\{\left[\operatorname{diag}\left(P_{j n}^{s}\right)+\left(P_{j n}^{s}-\operatorname{diag}\left(P_{j n}^{s}\right)\right)\right]\left[\operatorname{diag}\left(C_{k n}^{s}\right)+\left(B_{k n}^{s}-\operatorname{diag}\left(C_{k n}^{s}\right)\right)\right]\right\} \\
& =\operatorname{tr}\left\{\operatorname{diag}\left(P_{j n}^{s}\right) \operatorname{diag}\left(C_{k n}^{s}\right)+\left[P_{j n}^{s}-\operatorname{diag}\left(P_{j n}^{s}\right)\right]\left[C_{k n}^{s}-\operatorname{diag}\left(C_{k n}^{s}\right)\right]\right\}  \tag{C.13}\\
& =\operatorname{tr}\left(P_{j n, \xi}^{s} C_{k n, 1 / \xi}^{s}\right) \\
& =\operatorname{vec}^{\prime}\left(P_{j n, \xi}^{s}\right) \operatorname{vec}\left(C_{k n, 1 / \xi}^{s}\right)
\end{align*}
$$

where $P_{j n, \xi}^{s}=\xi \operatorname{diag}\left(P_{j n}^{s}\right)+\left[P_{j n}^{s}-\operatorname{diag}\left(P_{j n}^{s}\right)\right]$. By (11), (C.12) and (C.13),

$$
\begin{equation*}
G_{n}=-\frac{1}{n}\binom{\frac{1}{2} \omega_{n \xi}^{\prime}\left[\operatorname{vec}\left(C_{1 n, 1 / \xi}^{s}\right), \cdots, \operatorname{vec}\left(C_{k_{z}+2, n, 1 / \xi}^{s}\right), 0_{n^{2} \times k_{x}}\right]}{Q_{n}^{\prime} R_{n}\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), 0_{n \times 1}, \bar{Z}_{n}, X_{n}\right]} . \tag{C.14}
\end{equation*}
$$

For simplicity, let the $j$ th column of $R_{n}\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), 0_{n \times 1}, \bar{Z}_{n}, X_{n}\right]$ be $K_{j n}$. Denote $\tilde{K}_{j n}=$ $K_{j n}-\frac{1}{n} l_{n} l_{n}^{\prime} K_{j n}$, which is a vector with the sum of its elements equal to zero. Note that, as $P_{j n}$ 's have zero traces so that $d_{P_{j n}^{s}}^{\prime} l_{n}=0$, we have $\operatorname{vec}^{\prime}\left(P_{j n, \xi}^{s}\right) \operatorname{vec}\left(\operatorname{diag}\left(\tilde{K}_{j n}\right)\right)=\operatorname{tr}\left(P_{j n, \xi}^{s} \operatorname{diag}\left(\tilde{K}_{j n}\right)\right)=$ $\xi \operatorname{tr}\left(\operatorname{diag}\left(P_{j n}^{s}\right) \operatorname{diag}\left(\tilde{K}_{j n}\right)\right)=\xi d_{P_{j n}^{s}}^{\prime} \tilde{K}_{j n}=\xi d_{P_{j n}^{s}}^{\prime} K_{j n}=2 \xi d_{P_{j n}}^{\prime} K_{j n}$. Thus, by (C.11) and (C.14),

$$
\begin{equation*}
G_{n}=-\frac{1}{n} \Delta_{n}^{\prime} \Gamma_{n} \tag{C.15}
\end{equation*}
$$

where
$\Gamma_{n}=\left(\begin{array}{cc}\Gamma_{n, 11} & -\frac{\mu_{30}}{\sqrt{2} \xi_{0}^{4}}\left[\operatorname{vec}\left(\operatorname{diag}\left(\tilde{K}_{k_{z}+3, n}\right)\right), \cdots, \operatorname{vec}\left(\operatorname{diag}\left(\tilde{K}_{k_{z}+k_{x}+2, n}\right)\right)\right] \\ \frac{1}{\sigma_{0}} R_{n}\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), 0_{n \times 1}, \bar{Z}_{n}\right] & \frac{1}{\sigma_{0}} R_{n} X_{n}\end{array}\right)$

[^10]with $\Gamma_{n, 11}=\left[\operatorname{vec}\left(\frac{1}{\sqrt{2} \sigma_{0}^{2}} C_{1 n, 1 / \xi}^{s}-\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}} \operatorname{diag}\left(\tilde{K}_{1 n}\right)\right), \cdots, \operatorname{vec}\left(\frac{1}{\sqrt{2} \sigma_{0}^{2}} C_{k_{z}+2, n, 1 / \xi}^{s}-\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}} \operatorname{diag}\left(\tilde{K}_{k_{z}+2, n}\right)\right)\right]$. Hence, by (C.10) and (C.15), $G_{n}^{\prime} \Omega_{n}^{-1} G_{n}=\frac{1}{n} \Gamma_{n}^{\prime} \Delta_{n}\left(\Delta_{n}^{\prime} \Delta_{n}\right)^{-1} \Delta_{n}^{\prime} \Gamma_{n} \leq \frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}$ by the Cauchy-Schwarz inequality, and $G_{n}^{\prime} \Omega_{n}^{-1} G_{n}=\frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}$ if each column of $\Gamma_{n}$ lies in the column space of $\Delta_{n}$. As $\Gamma_{n}$ does not depend on $Q_{n}$ and $P_{j n}$ 's, $\lim _{n \rightarrow \infty}\left(\frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}\right)^{-1}$ is the lower bound for the asymptotic variances of OGMM estimators in Proposition 3.

We next investigate the selection of $Q_{n}$ and $P_{j n}$ 's so that the lower bound $\lim _{n \rightarrow \infty}\left(\frac{1}{n} \Gamma_{n}^{\prime} \Gamma_{n}\right)^{-1}$ can be attained. Let $\alpha_{1}, \ldots, \alpha_{k_{p}}$ be constants and $\alpha$ be a $k_{q} \times 1$ vector. By (C.11),

$$
\begin{equation*}
\Delta_{n}\left[\alpha_{1}, \cdots, \alpha_{k_{p}}, \alpha^{\prime}\right]^{\prime}=\binom{\frac{\sigma_{0}^{2}}{\sqrt{2}} \operatorname{vec}\left(P_{n, \xi}^{s}\right)}{\frac{\mu_{30}}{\sigma_{0}} d_{P_{n}}+\sigma_{0} Q_{n} \alpha} \tag{C.17}
\end{equation*}
$$

where $P_{n}=\sum_{j=1}^{k_{p}} \alpha_{j} P_{j n}$. For $1 \leq j \leq k_{z}+2$, letting (C.17) be equal to the $j$ th column of $\Gamma_{n}$ in (C.16) yields

$$
\begin{equation*}
\binom{\frac{\sigma_{0}^{2}}{\sqrt{2}} \operatorname{vec}\left(P_{n, \xi}^{s}\right)}{\frac{\mu_{30}}{\sigma_{0}} d_{P_{n}}+\sigma_{0} Q_{n} \alpha}=\binom{\operatorname{vec}\left(\frac{1}{\sqrt{2} \sigma_{0}^{2}} C_{j n, 1 / \xi}^{s}-\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}} \operatorname{diag}\left(\tilde{K}_{j n}\right)\right)}{\frac{1}{\sigma_{0}} K_{j n}} \tag{C.18}
\end{equation*}
$$

This is possible when

$$
\begin{aligned}
\frac{\xi \sigma_{0}^{2}}{\sqrt{2}} \operatorname{diag}\left(P_{n}^{s}\right) & =\frac{1}{\sqrt{2} \xi \sigma_{0}^{2}} \operatorname{diag}\left(C_{j n}^{s}\right)-\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}} \operatorname{diag}\left(\tilde{K}_{j n}\right), \\
\frac{\sigma_{0}^{2}}{\sqrt{2}}\left[P_{n}^{s}-\operatorname{diag}\left(P_{n}^{s}\right)\right] & =\frac{1}{\sqrt{2} \sigma_{0}^{2}}\left[C_{j n}^{s}-\operatorname{diag}\left(C_{j n}^{s}\right)\right], \\
\frac{\mu_{30}}{\sigma_{0}} d_{P_{n}}+\sigma_{0} Q_{n} \alpha & =\frac{1}{\sigma_{0}} K_{j n} .
\end{aligned}
$$

We may let $\alpha_{1}=\cdots=\alpha_{j-1}=0, \alpha_{j}=\frac{1}{\sigma_{0}^{4}}, \alpha_{j+1}=\cdots=\alpha_{k_{p}}=0$, and take $P_{j n}^{s}$ to be

$$
P_{j n}^{* s}=\left[C_{j n}^{s}-\operatorname{diag}\left(C_{j n}^{s}\right)\right]+\frac{1}{\xi^{2}} \operatorname{diag}\left(C_{j n}^{s}\right)-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{2}} \operatorname{diag}\left(\tilde{K}_{j n}\right) .
$$

The $j$ th column of $Q_{n}$ can be taken as $Q_{j n}^{*}=K_{j n}-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{C_{j n}}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \tilde{K}_{j n}$. Alternatively, we can use the square matrices in $P_{j n}^{* s}$ separately, so that we have the square matrices $C_{j n}^{s}-\operatorname{diag}\left(C_{j n}^{s}\right)$, $\operatorname{diag}\left(C_{j n}^{s}\right)$ and $\operatorname{diag}\left(\tilde{K}_{j n}\right)$, because $P_{j n}^{* s}$ is a linear combination of these matrices. If we use the IVs in $Q_{j n}^{*}$ separately, then we have the IVs $K_{j n}, d_{C_{j n}}$ and $\tilde{K}_{j n}$. As $\tilde{K}_{j n}=K_{j n}-\frac{1}{n} l_{n} l_{n}^{\prime} K_{j n}$, we can use the IVs $K_{j n}, d_{C_{j n}}$ and $l_{n}$ equivalently.

For $k_{z}+3 \leq j \leq k_{z}+k_{x}+2$, letting (C.17) be equal to the $j$ th column of $\Gamma_{n}$ in (C.16) yields

$$
\binom{\frac{\sigma_{0}^{2}}{\sqrt{2}} \operatorname{vec}\left(P_{n, \xi}^{s}\right)}{\frac{\mu_{30}}{\sigma_{0}} d_{P_{n}}+\sigma_{0} Q_{n} \alpha}=\left(\begin{array}{c}
-\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}}  \tag{C.19}\\
\frac{\operatorname{vec}}{}\left(\operatorname{diag}\left(\tilde{K}_{j n}\right)\right) \\
\frac{1}{\sigma_{0}} K_{j n}
\end{array}\right)
$$

This is possible when

$$
\frac{\xi \sigma_{0}^{2}}{\sqrt{2}} \operatorname{diag}\left(P_{n}^{s}\right)=-\frac{\mu_{30}}{\sqrt{2} \xi \sigma_{0}^{4}} \operatorname{diag}\left(\tilde{K}_{j n}\right)
$$

$$
\frac{\mu_{30}}{\sigma_{0}} d_{P_{n}}+\sigma_{0} Q_{n} \alpha=\frac{1}{\sigma_{0}} K_{j n} .
$$

We may let $\alpha_{1}=\cdots=\alpha_{j-1}=0, \alpha_{j}=-\frac{\mu_{30}}{2 \xi^{2} \sigma_{0}^{6}}, \alpha_{j+1}=\cdots=\alpha_{k_{p}}=0$, and take $P_{j n}^{s}$ to be $P_{j n}^{* s}=$ $2 \operatorname{diag}\left(\tilde{K}_{j n}\right)$. The $j$ th column of $Q_{n}$ can be taken as $Q_{j n}^{*}=K_{j n}+\frac{\mu_{30}^{2}}{2 \xi^{2} \sigma_{0}^{6}} \tilde{K}_{j n}$. Alternatively, if we use the IVs in $Q_{j n}^{*}$ separately, then we have the IVs $K_{j n}$ and $l_{n}$.

As $K_{j n}$ is the $j$ th column of $R_{n}\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), 0_{n \times 1}, \bar{Z}_{n}, X_{n}\right]$, we have, in particular, $Q_{2 n}^{*}=$ $-\frac{\mu_{30}}{\xi^{2} \sigma_{0}^{4}} d_{C_{2 n}}$, which can be taken as $d_{C_{2 n}}$ equivalently, and is redundant when $\mu_{30}=0$. In addition, when $\mu_{30}=0$, the square matrices $\operatorname{diag}\left(\tilde{K}_{j n}\right)$ for quadratic moments, where $k_{z}+3 \leq j \leq k_{z}+k_{x}+2$, are redundant, since they are from (C.19). Therefore, the results in the proposition follow.

## Appendix D Proof of Proposition 1 under weaker assumptions

Let $\|A\|$ be the spectral norm of a square matrix $A$, i.e., the square root of the largest eigenvalue of $A^{\prime} A$. We replace Assumptions 2 and 5 with the following two weaker assumptions respectively, and show that Proposition 1 still holds under the weaker assumptions.

Assumption D.1. The $W_{n}$ and $M_{n}$ have zero diagonals, and $\left\{W_{n}\right\},\left\{M_{n}\right\},\left\{S_{n}^{-1}\right\}$ and $\left\{R_{n}^{-1}\right\}$ are bounded in the spectral norm.

Assumption D.2. Elements of $Q_{n}$ are uniformly bounded constants, and $\left\{P_{j n}\right\}$ for $j=1, \ldots, k_{p}$ are bounded in the spectral norm.

We first prove the following lemma.
Lemma D.1. Let $\left\{A_{n}\right\}$ be a sequence of $n \times n$ nonstochastic matrices such that $\sup _{n}\left\|A_{n}\right\|<\infty, b_{n}$ be an $n \times 1$ vector of constants that are uniformly bounded, and $\epsilon_{n}=\left[\epsilon_{n 1}, \cdots, \epsilon_{n n}\right]^{\prime}$, where $\epsilon_{n i}$ 's are independent with mean zero. Then (i) $\frac{1}{n} b_{n}^{\prime} A_{n}^{\prime} \epsilon_{n}=o_{p}(1)$ and $\frac{1}{n} b_{n}^{\prime} A_{n} \epsilon_{n}=o_{p}(1)$, if $\sup _{i, n} \mathrm{E}\left(\epsilon_{n i}^{2}\right)<$ $\infty$; (ii) $\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=O(1)$ if $\sup _{i, n} \mathrm{E}\left(\epsilon_{n i}^{2}\right)<\infty$; and (iii) $\frac{1}{n} \epsilon_{n}^{\prime} A_{n} \epsilon_{n}-\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=o_{p}(1)$ if $\sup _{i, n} \mathrm{E}\left(\epsilon_{n i}^{4}\right)<\infty$.

Proof. (i) Denote $\Sigma_{n}=\operatorname{diag}\left(\sigma_{n 1}^{2}, \cdots, \sigma_{n n}^{2}\right)$, where $\sigma_{n i}^{2}=\mathrm{E}\left(\epsilon_{n i}^{2}\right)$. Let $A_{n}^{\prime} A_{n}=\Gamma_{n} \Lambda_{n} \Gamma_{n}^{\prime}$ be the spectral decomposition of $A_{n}^{\prime} A_{n}$, where $\Gamma_{n} \Gamma_{n}^{\prime}=I_{n}$ and $\Lambda_{n}$ is an $n \times n$ diagonal matrix of the eigenvalues of $A_{n}^{\prime} A_{n}$. The variance of $\frac{1}{n} b_{n}^{\prime} A_{n}^{\prime} \epsilon_{n}$ satisfies $\operatorname{var}\left(\frac{1}{n} b_{n}^{\prime} A_{n}^{\prime} \epsilon_{n}\right)=\frac{1}{n^{2}} b_{n}^{\prime} A_{n}^{\prime} \Sigma_{n} A_{n} b_{n} \leq \frac{c}{n^{2}} b_{n}^{\prime} A_{n}^{\prime} A_{n} b_{n}=$ $\frac{c}{n^{2}} b_{n}^{\prime} \Gamma_{n} \Lambda_{n} \Gamma_{n}^{\prime} b_{n} \leq \frac{c}{n^{2}} b_{n}^{\prime} b_{n} \lambda_{\max }\left(A_{n}^{\prime} A_{n}\right)=O\left(\frac{1}{n}\right)$, where $c$ is a constant and $\lambda_{\max }\left(A_{n}^{\prime} A_{n}\right)$ denotes the largest eigenvalue of $A_{n}^{\prime} A_{n}$. Thus, $\frac{1}{n} b_{n}^{\prime} A_{n}^{\prime} \epsilon_{n}=o_{p}(1)$. Similarly, the variance of $\frac{1}{n} b_{n}^{\prime} A_{n} \epsilon_{n}$ satisfies $\operatorname{var}\left(\frac{1}{n} b_{n}^{\prime} A_{n} \epsilon_{n}\right) \leq \frac{c}{n^{2}} b_{n}^{\prime} b_{n} \lambda_{\max }\left(A_{n} A_{n}^{\prime}\right)=\frac{c}{n^{2}} b_{n}^{\prime} b_{n} \lambda_{\max }\left(A_{n}^{\prime} A_{n}\right)=O\left(\frac{1}{n}\right)$. Thus, $\frac{1}{n} b_{n}^{\prime} A_{n} \epsilon_{n}=o_{p}(1)$.
(ii) Let $A_{n}=\left[a_{n, i j}\right]$. We have $\left|\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)\right|=\left|\frac{1}{n} \operatorname{tr}\left(A_{n} \Sigma_{n}\right)\right|=\left|\frac{1}{n} \sum_{i=1}^{n} a_{n, i i} \sigma_{n i}^{2}\right| \leq \frac{c}{n} \sum_{i=1}^{n}\left|a_{n, i i}\right| \leq$ $c \sqrt{\frac{1}{n} \sum_{i=1}^{n} a_{n, i i}^{2}}$, where $c$ is a constant and the last inequality follows by the Cauchy-Schwarz
inequality. Then, $\left|\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)\right| \leq c \sqrt{\frac{1}{n} \sum_{i=1}^{n} \sum_{j=1}^{n} a_{n, i j}^{2}}=c \sqrt{\frac{1}{n} \operatorname{tr}\left(A_{n}^{\prime} A_{n}\right)} \leq c\left\|A_{n}\right\|$. Thus, $\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=O(1)$.
(iii) By Lemma 2(3) in Jin and Lee (2012), the variance of $\epsilon_{n}^{\prime} A_{n} \epsilon_{n}$ is $\operatorname{var}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=\sum_{i=1}^{n} a_{n, i i}^{2}\left[\mathrm{E}\left(\epsilon_{n i}^{4}\right)-\right.$ $\left.3 \sigma_{n i}^{4}\right]+\operatorname{tr}\left[\Sigma_{n} A_{n} \Sigma_{n}\left(A_{n}+A_{n}^{\prime}\right)\right]$. Thus,

$$
\begin{aligned}
\operatorname{var}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right) & \leq c_{1} \sum_{i=1}^{n} a_{n, i i}^{2}+\frac{1}{2} \operatorname{tr}\left[\Sigma_{n}^{1 / 2}\left(A_{n}+A_{n}^{\prime}\right) \Sigma_{n}\left(A_{n}+A_{n}^{\prime}\right) \Sigma_{n}^{1 / 2}\right] \\
& \leq n c_{2}+c_{3} \operatorname{tr}\left[\Sigma_{n}^{1 / 2}\left(A_{n}+A_{n}^{\prime}\right)\left(A_{n}+A_{n}^{\prime}\right) \Sigma_{n}^{1 / 2}\right] \\
& =n c_{2}+c_{3} \operatorname{tr}\left[\left(A_{n}+A_{n}^{\prime}\right) \Sigma_{n}\left(A_{n}+A_{n}^{\prime}\right)\right] \\
& \leq n c_{2}+c_{4} \operatorname{tr}\left[\left(A_{n}+A_{n}^{\prime}\right)\left(A_{n}+A_{n}^{\prime}\right)\right] \\
& \leq n c_{2}+n c_{4}\left\|A_{n}+A_{n}^{\prime}\right\|^{2} \\
& \leq n c_{2}+n c_{4}\left(\left\|A_{n}\right\|+\left\|A_{n}^{\prime}\right\|\right)^{2} \leq n c_{5}
\end{aligned}
$$

where $c_{j}$ 's are constants, and the last inequality uses $\left\|A_{n}\right\|=\left\|A_{n}^{\prime}\right\|$. Hence, $\operatorname{var}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=O(n)$ and $\frac{1}{n} \epsilon_{n}^{\prime} A_{n} \epsilon_{n}-\frac{1}{n} \mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=o_{p}(1)$.

As can be seen from the proof of Proposition 1 in Appendix C, replacing Assumptions 2 and 5 by Assumptions D.1-D. 2 only affects the terms with the forms in the above lemma. Since the above lemma shows that the orders of those terms do not change, Proposition 1 still holds.

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[^1]:    ${ }^{1}$ A reduced form is also assumed in Liu (2012) when the LIML estimator is considered. It is needed to form a proper likelihood function.

[^2]:    ${ }^{2} \mathrm{~A}$ list of notations is provided in Appendix A for convenient reference.

[^3]:    ${ }^{3}$ In the homoskedastic case, as pointed out by an anonymous referee, we may omit the subscript $n$ of $\epsilon_{n i}$ 's, e.g., denote $\epsilon_{n}=\left[\varepsilon_{1}, \cdots, \varepsilon_{n}\right]^{\prime}$. But in the heteroskedastic case, we need the subscript $n$ for $\epsilon_{n i}$ 's, in order to show that $\epsilon_{n i}$ can have different variances for different $n$.

[^4]:    ${ }^{4} \mathrm{As}\left(\mu_{40}-\sigma_{0}^{4}\right) \sigma_{0}^{2}=\mathrm{E}\left[\left(\epsilon_{n i}^{2}-\sigma_{0}^{2}\right)^{2}\right] \cdot \mathrm{E}\left(\epsilon_{n i}^{2}\right) \geq \mu_{30}^{2}$ by the Cauchy-Schwarz inequality, $\frac{\mu_{40}}{\sigma_{0}^{4}}-1-\frac{\mu_{30}^{2}}{\sigma_{0}^{6}} \geq 0$.

[^5]:    ${ }^{5}$ When disturbances are heteroskedastic, the best selection of linear and quadratic moments might exist (see Debarsy et al., 2015, for the theoretically best moments of the matrix exponential spatial specification and SAR models with no endogenous regressors), but a best GMM estimator would not be feasible due to the unknown $\Sigma_{n}$ (Lin and Lee, 2010).

[^6]:    ${ }^{6}$ For this estimator, in Assumptions 4, 6, 8, 10 and 11, $Q_{n}$ and $P_{j n}$ become, respectively, $Q_{n}^{*}$ and $P_{j n}^{*}$. Some of the assumptions can be directly verified, e.g., some elements of $Q_{n}^{*}$ can be shown to be uniformly bounded, but some are not, e.g., the orders of terms involving $\check{Z}_{n}$.
    ${ }^{7}$ When $X_{n}$ contains $l_{n}$ as a column, which corresponds to the intercept term, and $M_{n}$ is normalized to have row sums equal to one, $R_{n} X_{n}$ generates a column of constants. In this situation, $l_{n}$ should be removed from $Q_{n}^{*}$ to avoid multicolinearity.

[^7]:    ${ }^{8}$ Note that BGMM in the heteroskedastic case is no longer the theoretically best GMM estimator with linear and quadratic moments. In the heteroskedastic case, BGMM uses moment conditions modified from the best linear and quadratic moments for the homoskedastic case, where the IV matrix is the same and the quadratic matrices are modified to have zero diagonals.

[^8]:    ${ }^{9}$ For an $n \times n$ matrix $A_{n}$, note that $\mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=\sigma_{0}^{2} \operatorname{tr}\left(A_{n}\right)$ if $\epsilon_{n i}$ 's are homoskedastic, and $\mathrm{E}\left(\epsilon_{n}^{\prime} A_{n} \epsilon_{n}\right)=\operatorname{tr}\left(A_{n} \Sigma_{n}\right)$ if $\epsilon_{n i}$ 's are heteroskedastic. We keep the expectation in (C.1) for simplicity.
    ${ }^{10} \mathrm{We}$ thank an anonymous referee for pointing out this.

[^9]:    ${ }^{11}$ We may permute the columns of $\left[T_{n}\left(\bar{Z}_{n} \gamma_{0}+X_{n} \beta_{0}\right), \bar{Z}_{n}\right]$ to derive a new matrix $A_{n}$, and assume that the submatrix formed by the last $\left(k_{x}+k_{0}\right)$ columns of $\lim _{n \rightarrow \infty} \frac{1}{n} Q_{n}^{\prime} R_{n}(\rho)\left[A_{n}, X_{n}\right]$ has full column rank for any $\rho$ in its parameter space. Then the argument below is similar.

[^10]:    ${ }^{12}$ When defining the best moments later, the constant $\sigma_{0}^{2}$ can be removed. The $C_{2 n}$ in this proof has an extra $\sigma_{0}^{2}$ compared with that in Proposition 4.

